## Programmable operation terminal for MODBUS OPA2-MOD

General description
The OPAR-MDD is a programmable operation terminal with an isolated RS485 MODBUS communication.
The operation terminal is communicating in slave mode. It may be used to control fan coil or VAV zones. Up
to 5 zones may be controled with one terminal
Features

- RS485 2-wire MODBUS standard in accordance to EIATIA 485
- Slave type of communication
- Supports up to 127 nodes on one network
- Galvanic isolated bus connection
- Gavvanic isolated bus connection
- RTU with CRC16 checksum
- ASCII with LRC checksum
- Parity: No parity, odd or even parity.

- LED indicators

Communication Specification

| Communication standard | Modbus (www.modbus.org) |
| :---: | :---: |
| Default setting | 19200 Baudrate, RTU 8 data bits, 1 even parity bit, 1 stop bit |
| Communication speed | 4800, 9600, 19200, 38400 |
| Protocol | RTU with CRC16 checksum ASCII with LRC checksum |
| Parity bit | no parity, even parity, odd parity |

By default, RTU uses 8 data bits, 1 parity bit with even parity and 1 stop bit; ASCII mode uses 7 data bits,
parity bit with even parity, and 1 1 stop bit parity bit with even parity, and 1 stop bit.
Both modes support "No Parity" mode, in these cases a ${ }^{\text {nds }}$ stop bit is used to keep the byte length (11 bit tor
RTU and 10 bit for ASCll, including the Start and Stop bits) unchanged in accordance with the Modbus specification.

03 (0x03): Read multiple registers
06 (0x060: Write single register
06 (0x06): Write single register
16 (0x10): Write multiple register
In commands 03 and 16 the allowed number of registers ranges from 1 to 32 . Athough Modbus specification would allow more registers to be read and written, a maximum of 32 Modbus registers are supported in on
packet. One Modbus register is 16 bits wide. The Modbus slave transmits the values as siged 16 bit packet. One Modbus register is 16 bits wide. The Modbus slave transmits the values as signed 16 bit
integers. The least significant digitit of the transmitted number is always the first digit below the decimal poin and
anghis result in the following range of numbers that the slave module is able to transmit: from -9999.9 to

In an event of an out-of-range command addressing or an unsupported command, the Modbus slav
responds with an exception message according to the Moodbus specification.

| Model | Item\# | Display | RT | DI | rH | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| OPA2-MOD | 40-50 0014 | yes | 1 | 2 | . | Modbus communication module with one internal temperature and one external temperature input plus two binary inputs. |
| PA2-MOD | 40-50 0053 | yes | 1 | 2 | 1 | As above with internal humidity sensor 3\% accuracy. |

Vector
Operation terminal for MODBUS OPA2-MOD
Vector

## Technical Specification

## mportant notice and safety advice

This device is for use as operating controls. It is not a safety device! Where a device failure endangers human life
and/or property, it is the responsibility of the client, installer and system designer to add additional safety devices to and/or property, it it the responsibility of the client, installe
prevent a system failure caused by such a device failure.
lgnoring specifications and local regulations may cause equipment damage and endangers life and property.
Tampering with the device and misapppication will vous equipmen


Dimensions [mm](in)



Line polarization: Line polarization:
The deve perce neds line polarization. One pair of
resistors may be connected on the RS-485 resistors may be connected on the RS-485
balanced pair: balanced pair:
-a Pull-Up Resistor to a 5 V Voltage on D1
circuit. Circuit
-a Pul-Down Resistor to the common circuit on
Do circuit. This should be done only once at the Do circuit. This should be done only once at the master only. The value of those resistors
be between 450 Ohms and 650 Ohms. 650 be between 450 Ohms and 650 ohms. 650
Ohms resistors value may allow a higher number Ohms resistors value may allow

Note:
Power GND $\neq$ Modbus common!

On last node on either end of bus only

| scription: |  |  |
| :---: | :---: | :---: |
| GND | Power supply: | ${ }^{\text {OV]; common for power supply }}$ |
| 24 V | Power supply: | 24 V AC or 24 V DC |
| D11 | Passive input: | Binary input, keep open or switch to ov |
| D12 | Passive input: | Binary input, keep open or switch to oV |
| RT1 | Passive input: | NTC 10k $\Omega$ @ $25^{\circ} \mathrm{C}\left(777^{\circ} \mathrm{F}\right)$ or open conta |
| $\stackrel{(+)}{(-)}$ | RS485 RS485 | Modbus + |
| REF | RS485 | Modbus Re |

## Mounting location

On an easy accessible interior wall, approx. $1.5 \mathrm{~m}\left(4.5^{\prime}\right)$ above the floor in an area of
Avoid exposure to to direct sunlight or other heat sources, e.g. the area above radiators and

- Avoid exposure to direct sunifgher
- Avoid locations behind doors, outside walls and below or above air discharge gis

Installation

1. Connect the wires to the terminals of the power case according to wiring diagram
2. Install the mounting plate to the flush mounting box. Make sure that the nipple with the front holding screw is facing to the ground. Make sure the mounting screw heads do not stand out
3. $\quad \begin{aligned} & \text { more than } 5 \mathrm{~mm}\left(0.2^{\prime \prime} \text { ) of the surface of the mounting plate. }\right. \\ & \text { Slide the two latches located on the top of the front part into the hooks at the upper side of }\end{aligned}$
4. the mounting plate.
5. Carefully lower the front part until the interconnector reaches the mounting-plate. Continue



Display and Operation


| Operation mode symbols |  | Control symbols |  |
| :---: | :---: | :---: | :---: |
|  | Comfort (occupied) | Heating (reverse) active |  |
|  | Standby (unoccupied): |  | Cooling (direct) active |
| OFF | Energy hold off | Manual overide, |  |
|  |  | ※ | Fan active |

Standard display in OFF mode

- Active when UP/DOWN or OPTION have not been pressed for 30 seconds and unit is in Contents
Standard display in ON mode
- Active when Up/Down or OPTION have not been pressed for 30 seconds and unit is in ON Contents may be chosen.
Set display
Active when changing set points. Large digits show input value. Small digits show set point.
Vertical bars show output value. All values and allowable set point ranges may be chosen.
Symbols
Select which symbol to show. Active symbols in OFF mode are selected by bitmap.
Power failure
Error message
All parameters and set points are memorized and do not need to be re-entered.
Erri: A communication timeout occurred. The operation terminal did communicate successstully fo
the time period defined with CP18 (1022). Verity wiring or operation of Modbus master device.
To disable this error: set CP18 (1022) to 0.
$\begin{array}{ll}\text { Err2: } & \text { The selected sensor is damaged or missing. } \\ \text { NA: } & \text { The selected sensor is not enabled }\end{array}$
NA: The change of setpoint or operation mode is disabled or the remote disable The change of setp
function is active.


## Configuration parameters for firmware version 1.2

The OPA2-MOD can be fine-tuned with a simple parameter setup routine. The parameters can be changed on the Access to parameters
The parameters can be changed as follow

1. Press UP/DOWN buttons simultaneously for three seconds. Press the OPTION button to start login.

CODE is shown on the upper digits.
3. Select 009 using UP/DOWN buttons.
4. Press OPTION atter selecting the correct code. Now the Software Version and Revision is displayed
5. Select the parameters by pressing the UP/DOWN buttons. Press the OPTION button to adjust the value with
6. Press the POWER to leave the menu

## Setup parameters

| Parameter | Description | Range | Default |
| :---: | :---: | :---: | :---: |
| CP 00 | Communication address (must be unique in network) | $1 . .255$ | 1 |
| CP 01 | $\begin{aligned} & \hline \text { Baud rate: } \\ & 0=19200 \\ & 1=4800 \\ & 2=9600 \\ & 3=19200 \\ & 4=38400 \\ & \hline \end{aligned}$ | 0.... 4 | 0 |
| CP 02 | Parity mode: $0=$ No Parity, 1 =Even Parity, 2 = Odd Parity | 0...1 | 1 |
| CP 03 | Mode of communication : $0=$ RTU, $1=$ ASCII | $0 . . .1$ | 0 |
| CP 04 | Allow changing of communication address through broad cast command <br> $0=$ Not allowed, $1=$ Allowed | 0...1 | 0 |
| CP 05 | Total number of groups <br> $0=$ one group with fan speed selection on right key <br> $1=$ one group <br> $2=$ two groups <br> $3=$ three groups <br> $5=$ five groups | 0... 5 | 1 |
| CP 06 | Setpoint change enable $0=$ disabled, 1 = enabled | 0...1 | 1 |
| CP 07 | Operation mode change ON/OFF enabled $0=$ disabled, $1=$ enabled | 0...1 | 1 |
| CP 08 | Operation mode change occupied / unoccupied enabled <br> $0=$ disabled, $1=$ enabled | 0...1 | 1 |
| CP 09 | $24 \mathrm{~h} / 12 \mathrm{~h}: 0=24 \mathrm{~h}, 1=12 \mathrm{~h}$ (AM/PM) | 0...1 | 0 |
| CP 10 | AM / PM flag (applies if CP 09 is $1-12 \mathrm{~h}$ mode) $0=\mathrm{AM}, 1=\mathrm{PM}$ | 0...1 | 0 |
| CP 11 | Celsius/Fahrenheit, $0=$ Celsius, $1=$ Fahrenheit | $0 . .1$ | 0 |
| CP 12 | Timeout in seconds to idle mode | 1...255 | 30 |
| CP 13 | Idle mode, $\mathbf{0}=$ disabled, 1 = enabled If enabled shows a specific screen if no key is pressed for the time defined in CP12 | 0...1 | 0 |
| CP 14 | Maximum number of FAN speeds This setting applies for CP05 $=0$ (one group with fan speed). | 1...4 | 3 |
| CP 15 | Humidity sensor Offiset | -12,7...12.7\% | 0 |
| CP 16 | Internal NTC sensor Offset | $-12.7 . .12 .7^{\circ} \mathrm{C}$ | 0 |
| CP 17 | External NTC sensor Offset | -12.7...12.7 ${ }^{\circ} \mathrm{C}$ | 0 |
| CP 18 | Modbus communication timeout: If there is no communication within the amount of seconds specified here, "Er1" is shown on the small digits. Setting the value to " 0 " disables this feature. | 0...1000s | 60s |
| CP 19 | Delay for remote disable function. Useful for key card switches or window contacts connected to digital inputs. <br> This function is activated in the setup for digital inputs. | 0...255s | 10s |
| CP 20 | Delay for occupied/unoccupied changeover contact. Defines the timeout required to switch to unoccupied mode while there is no activity signaled by the motion detector connected to one of the digital digital inputs. | 0...9999min | 10 min |

Address list
Terminal setup

| Address | Type | RW | Contents |
| :---: | :---: | :---: | :---: |
| 1000 | 8bit | R | Hardware version / type |
| 1001 | 8bit | R | Software version |
| 1002 | 8bit | R | Software revision |
| 1003 | 8bit | RW | Communication address (must be unique in network)(factory default is " 1 ") |
| 1004 | Selection | RW | $\begin{aligned} & \text { Baud rate: } \\ & 0=19200 \\ & 1=4800 \\ & 2=9600 \\ & 3=19200 \\ & 4=38400 \\ & \hline \end{aligned}$ |
| 1005 | bit | RW | Parity mode: $0=$ No Parity, $1=$ Even Parity, $2=$ Odd Parity |
| 1006 | bit | RN | Mode of communication : $0=$ RTU, $1=$ ASCII |
| 1007 | bit | RW | Allow changing of communication address through broad cast command. (will reset automatically after 30 seconds) = Not allowed, 1 = Allowed |
| 1008 | selection | RW | Total number of groups <br> $0=$ one group with fan speed selection on right key <br> 1 = one group <br> $2=$ two groups <br> = three groups <br> 4 = four groups <br> 5 = five groups |
| 1009 | bit | RN | Setpoint change enable $0=$ disabled, 1 = enabled |
| 1010 | bit | RW | Operation mode change ON/OFF enabled 0 = disabled, $1=$ enabled |
| 1011 | bit | RW | Operation mode change occupied / unoccupied enabled 0 = disabled, 1 = enabled |
| 1012 | BCD | RW | Clock with hours and minutes in BCD format |
| 1013 | bit | RW | $24 \mathrm{~h} / 12 \mathrm{~h} \mathrm{Clock} \mathrm{mode:} 0=24 \mathrm{~h}, 1=12 \mathrm{~h}$ (AMPM) |
| 1014 | bit | RW | AM/PM flag: $0=A M, 1=P M$ |
| 1015 | bit | RW | Celsius/Fahrenheit: $0=$ Celsius, $1=$ Fahrenheit |
| 1016 | byte | RW | Timeout in seconds to idle mode. (1... 255 seconds) |
| 1017 | bit | RW | Idle mode, $0=$ disabled, $1=$ enabled <br> If enabled shows a specific screen if no key is pressed for the ime defined in 1016 |
| 1018 | byte | RW | Maximum number of FAN speeds (1...4) (3) $\qquad$ with fan speed" with fan spe $(1008=0)$. |
| 1019 | byte signed | RW | Humidity sensor user programmable offset (12,7...0...12,7 \%) |
| 1020 | byte signed | RW | Internal NTC user programmable offset ( $\left.-12,7 . .0 . . .12,7^{\circ} \mathrm{C}\right)$ |
| 1021 | byte signed | RW | External NTC user programmable offset ( $-12,7 \ldots 0 . .12,7^{\circ} \mathrm{C}$ ) |
| 1022 | 16bit | RW | Modbus timeout for Err in in seconds. (0...60... 1000 seconds) If there is no communication within the amount of seconds specified here, "Err1" is shown on the small digits. Setting the value to "0" disables this feature. |
| 1023 | byte | RW | Remote disable delay for digital inputs ( $0 \ldots . .10 \ldots 255$ seconds) Useful for key card switches or window contacts connected 0 digital inputs. <br> This function is activated with address 10300 /or 10400. |
| 1024 | 16 bit | RN | Occupied/unoccupied changeover delay for digital inputs (0...10... 9999 minutes) efines the timeout required to switch to unoccupied mode while there is no activity signaled by the motion detector activated with address 10300 /or 10400. |

Operation state, symbols \& alarms

| Address | Type | R/W | Contents |
| :---: | :---: | :---: | :---: |
| 100 | 8bit | R | "Something Changed" flag. Gets the group ID value whenever a setpoint gets changed in a group. Is always written to " 0 " on any write. |
| 2000 | bit | RW | $\begin{aligned} & \begin{array}{l} \text { Operation state ON } / \text { OFF } \\ 0=0 \text { OFF } \\ 1=0 N \end{array} \\ & \hline \end{aligned}$ |
| 2001 | bit | RW | $\begin{aligned} & \text { Operation state occupied / unoccupied } \\ & 0=\text { Unoccupied } \\ & 1=\text { Occupied } \end{aligned}$ |
| 2002 | bit | RW | Maximum number of fan speeds (1...4) (3) |
| 2003 | 8bit | RW | Actual fan speed (0-4) |
| 2004 | bit | RW | Show fan (0) |
| 2005 | bit | RW | Show alarm symbol (0) |
| 2006 | bit | RW | Show alarm string (0) |
| 2007 | bit | RW | Show heat (0) |
| 2008 | bit | RW | Show cool (0) |
| 2009 | bit | RW | Show occupied (0) |
| 2010 | bit | RW | Show unoccupied (0) |
| 2011 | 16 bit | RW | Show arrow 0-10 LSb = Arrow 1 on the left (0) |
| 2012 | 8bit (ASCII) | RW | text string alarm letter 1: |
| 2013 | $\begin{aligned} & \text { mbit } \\ & (\text { ASCII) } \end{aligned}$ | RW | text string alarm letter 2: |
| 2014 | $\begin{aligned} & \text { Rit } \\ & \text { (ASCII) } \end{aligned}$ | RW | text string alarm letter 3: |
| 2015 | 8bit (ASCII) | RW | text string alarm letter 4: |
| 2016 | bit | RW | A flag to define where the alarm text shall be displayed <br> $0=$ nowhere <br> 1 = large digits <br> 2 = small digits |
| 2017 | bit | RW | Show time symbol (0) |
| 2018 | bit | RW | Show ove |

Display in idle mode
If enabled with address 1017(CP13), this screen is shown if no key is pressed for the time defined in


| Address | Type | Contents |
| :---: | :---: | :---: |
| 4000 | Selection | ```Contents of large digits: 0 = empty 1 = text string ON 2 = value group 1 (5001) 3 = setpoint group 1 (5004 or 5005 depending on occupied/unoccupied state) 4 = value group 2 (6001) 5 = setpoint group 2 (6004 or 6005 depending on occupied/unoccupied state) 6 = value group 3 (7001) 7 = setpoint group 3 (7004 or 7005 depending on occupied/unoccupied state) 8 = value group 4 (8001) 9 = setpoint group 4 (8004 or 8005 depending on occupied/unoccupied state) 10 = value group 5 (9001) 11 = setpoint group 5 (9004 or 9005 depending on occupied/unoccupied state) 12 = Clock 13 = Alarm text 14 = internal NTC 15 = external NTC 16 = humidity value 17 = digital input 1. 18 = digital input 2.``` |
| 4001 | Selection | ```Contents of small digits: 0= empty 1 = text string ON 2 = value group 1 (5001) 3 = setpoint group 1 (5004 or 5005 depending on occupied/unoccupied state) 4 = value group 2 (6001) 5 = setpoint group 2 (6004 or 6005 depending on occupied/unoccupied state) 6 = value group 3 (7001) 7 = setpoint group 3 (7004 or 7005 depending on occupied/unoccupied state) 8= value group 4 (8001) 9 = setpoint group 4 (8004 or 8005 depending on occupied/unoccupied state) 10 = value group 5 (9001) 11 = setpoint group 5 (9004 or 9005 depending on occupied/unoccupied state) 12 = Clock 13 = Alarm text 14 = internal NTC 15 = external NTC 16 = humidity value 17 = digital input 1. 18= digital input 2.``` |
| 4002 | Selection | Contents of vertical bar: $0=$ empty $1=$ bar 1 $2=$ bar 2 $3=$ bar 3 $4=$ bar 4 $5=$ bar 5 |
| 4003 | 8bit (ASCII) | text string ON letter 1: |
| 4004 | $\begin{aligned} & \text { 8bit } \\ & \text { (ASCII) } \end{aligned}$ | text string ON letter 2: 0 |
| 4005 | 8bit (ASCII) | text string ON letter 3: N |
| 4006 | 8bit (ASCII) | text string ON letter 4: |


| Address | Type | RW | Contents |  |
| :---: | :---: | :---: | :---: | :---: |
| 5000 | Selection | RW | Contents of large digits: $0=\text { empty }$ <br> $=$ text string group 1 <br> $2=$ value <br> mode) <br> 4 = Alarm text <br> 5 = internal NTC <br> 6 = external NTC <br> $7=$ humidity value <br> $9=$ digital input 2. | depending on operation |
| 5001 | ${ }^{16 \text { bit }}$ | RW | Value of large digits |  |
| 5002 | Selection | RW | $\begin{gathered} \hline \text { Unit of digits } \\ 0=\text { do unit } \\ 1=\% \\ 2=\circ \\ 3=\mathrm{Ca} \end{gathered}$ |  |
| 5003 | Selection | RW |  |  |
| 5004 | $\begin{aligned} & 16 \text { bit } \\ & \text { signed } \end{aligned}$ | RW | Comfort setpoint x 10 |  |
|  |  |  | Modbus value: 200 | Display value: 20.0 |
| 5005 | $\begin{aligned} & \hline 16 \text { bit } \\ & \text { signed } \end{aligned}$ | RW | Standby setpoint $\times 10$ |  |
|  |  |  | Modbus value: 200 Display value: 20.0 <br> Setooinstep $\times 10$  |  |
| 5006 | $\begin{aligned} & 16 \text { bit } \\ & \text { signed } \end{aligned}$ | RW |  |  |
|  |  |  | Modbus value: 1, 5, 10, 20, 50 | Display value: $0.1,0.5,1$, <br> 2,5 |
| 5007 | 16 bitsigned | RW | Low setpoint limit x 10 |  |
|  |  |  | Modbus value: 160 | Display value: 16.0 |
| 5008 | 16 bitsigned | RW | High setpoint limit $\times 10$ |  |
|  |  |  | Modbus value: 320 | Display value: 32.0 |
| 5009 | 8 bit | RW | Vertical bar 0-100 in steps of 10 |  |
|  |  |  | Modbus value: 10 | Verrical bars: 1 |
| 5010 | 8bit (ASCII) | RW | Text string letter 1 |  |
| 5011 | 8 bit (ASCII) | RW | Text string letter 2 | L |
| 5012 | 8bit (ASCII) | RW | Text string letter 3 | P |
| 5013 | 8bit (ASCII) | RW | Text string letter 4 | 1 |

Display group 2-5
As above with following addresses:
Group $2=6000-6013$
Group $3=7000-7013$
Group $4=8000-813$
Group $5=9000-9013$

| Input contiguration |  |  |  |
| :---: | :---: | :---: | :---: |
| Address | Type | RW | Contents |
| 10000 | bit | RW | Enable temperature input $0=$ sensor disabled <br> 1 = Sensor enabled |
| 10001 | bit | R | $\begin{gathered} \text { Emror state of input } \\ 0=0 \\ 1=\text { error } \\ \hline \end{gathered}$ |
| 10002 | 16 bit | R | Measured temperature input value |
| 10003 | 16 bit signed | RW | Internal temperature sensor programmable offset ( $-12,7 \ldots . . . .12,7^{\circ} \mathrm{C}$ ) |
| 10100 | bit | RW | Humidity input enabled (for -H type only) <br> 0 = sensor disabled <br> 1 = Sensor enabled |
| 10101 | bit | ${ }^{\text {R }}$ | Error state of input (for -H type only) $0=0 \mathrm{~K}$ $1=$ error |
| 10102 | 16 bit signed | R | Measured humididy input value (for - H type only) |
| 10103 | $\begin{aligned} & \begin{array}{l} \text { nigntit } \\ \text { signed } \end{array} \\ & \hline \text { sigd } \end{aligned}$ | RW | Internal humidity sensor programmable offset (-12,7...0...12,7\%) |
| 10200 | selection | RW | Enable external temperature sensor $0=$ sensor disabled $1=$ Sensor enabled |
| 10201 | bit | RW | $\begin{gathered} \hline \text { Error state of input } \\ 0=0 \mathrm{k} \\ 1=\text { error } \\ \hline \end{gathered}$ |
| 10202 | 16 bit signed | R | Value of external temperature input |
| 10203 | 16 bit signed | RW | External temperature sensor programmable offset ($12,7 \ldots 0 \ldots 12,7^{\circ} \mathrm{C}$ ) |
| 10300 | bit | RW | Digital input " 1 " function: <br> 0 : Input in normal digital mode <br> 1: Remote disable: Key card or Window contact <br> 2: Occupied / Unoccupied changeover: Motion detector |
| 10301 | bit | R | Digital input 1 value |
| 10302 | byte | RW | Digital input 1 open character 01 |
| 10303 | byte | RW | Digital input 1 open character 02 |
| 10304 | byte | RW | Digital input 1 open character 03 |
| 10305 | byte | RW | Digital input 1 open character 04 |
| 10306 | byte | RW | Digital input 1 grounded character 01 |
| 10307 | byte | RW | Digital input 1 grounded character 02 |
| 10308 | byte | RW | Digital input 1 grounded character 03 |
| 10309 | byte | RW | Digital input 1 grounded character 04 |
| 10400 | bit | RW | Digital input 2 function: <br> 0 : Input in normal digital mode <br> 1: Remote disable: Key card or Window contact <br> 2: Occupied / Unoccupied changeover: Motion detector |
| 10401 | bit | R | Digital input 2 value |
| 10402 | byte | RW | Digital input 2 open character 01 |
| 10403 | byte | RW | Digital input 2 open character 02 |
| 10404 | byte | RW | Digital input 2 open character 03 |
| 10405 | byte | RW | Digital input 2 open character 04 |
| 10406 | byte | RW | Digital input 2 grounded character 01 |
| 10407 | byte | RW | Digital input 2 grounded character 02 |
| 10408 | byte | RW | Digital input 2 grounded character 03 |
| 10409 | byte | RW | Digital input 2 grounded character 04 |

$\rightarrow \quad \begin{aligned} & \text { Use Remote disable for key cards or window contacts. If the digital input ts opened the device will switch to } \\ & \text { OFF mode atter the delay defined with address } 1023 \text { (CP19 ) has expired. Closing the contact will switch the }\end{aligned}$ OFF mode atter the delay defined with address 1023 (CP19) h
device back on immediately. The delay is defined in seconds.
$\rightarrow \quad$ Use occupied/unoccupied changeover with key card switches and occupancy sensors. The device will be in occupied mode as long as the digital input is connected to signal ground. Once the input is opened it will
switch to unoccupied mode after the delay defined with address 1024 (CP20) has expired. The delay is switch to unoccupied
defined in minutes.

| Fan strings |  |  |  |
| :---: | :---: | :---: | :---: |
| Address | Type | R/W | Contents |
| 11000 | byte | RW | FAN string 0 character 1 ("A") |
| 11001 | byte | RW | FAN string 0 character 2 ("u") |
| 11002 | byte | RW | FAN string 0 character 3 ( (t") |
| 11003 | byte | RW | FAN string 0 character 4 ("0") |
| 11004 | byte | RW | FAN string 1 character 1 ("F") |
| 11005 | byte | RW | FAN string 1 character 2 ("A") |
| 11006 | byte | RW | FAN string 1 character 3 ("N") |
| 11007 | byte | RW | FAN string 1 character 4 ("1") |
| 11008 | byte | RW | FAN string 2 character 1 ("F") |
| 11009 | byte | RW | FAN string 2 character 2 ("A") |
| 11010 | byte | RW | FAN string 2 character 3 ("N") |
| 11011 | byte | RW | FAN string 2 character 4 ("2") |
| 11012 | byte | RW | FAN string 3 character 1 ("F") |
| 11013 | byte | RW | FAN string 3 character 2 ("A") |
| 11014 | byte | RW | FAN string 3 character 3 ("N") |
| 11015 | byte | RW | FAN string 3 character 4 ("3") |
| 11016 | byte | RW | FAN string 4 character 1 ("") |
| 11017 | byte | RW | FAN string 4 character 2 ("O") |
| 11018 | byte | RW | FAN string 4 character 3 ("F") |
| 11019 | byte | RW | FAN string 4 character 4 ("F") |



