TCI-W13-H, TCI-W23-H wall mounted universal controller with internal temperature and humidity sensor

General description

The TCI-W is a stand-alone wall mounted electronic universal controller with two autonomous control loops. Each control loop may use up to 2 PID sequences and 6 binary sequences. The TCI-W13 features 1 independent control loop, 1 universal input, 1 binary relay output and 2 analog outputs, the TCI-W23 offers 2 independent control loops, 1 universal input, 1 passive input, 1 binary relay output and 2 analog outputs. A detailed configuration is possible by following a simple setup routine. The TCI can be configured using the standard operation terminal. No special tool or software is required.

Ordering, name convention

| TCI-W23-U | Optional functions and hour | sing |
|-----------|-----------------------------|---|
| | Housing | U = 2 x 4" type housing, blank = square housing |
| | In-/outputs: | 1 = 1UI, 1DOR, 2AO, 2 = 1UI, 1Passive In, 1DOR, 2AO |
| | Control loops: | 1 = 1 control loop, 2 = 2 control loops |
| | Mounting: | W = Wall mounted |
| L | Series indication | TCI |

| Item name | Item code | Loop | Int. temperature | Int. humidity | UI | тι | DO Relays | AO | Option |
|-----------|------------|------|---------------------|------------------|----|----|--------------|----|--------------|
| TCI-W11 | 40-10 0073 | 1 | 1 | 0 | 1 | 0 | 2 | 1 | Standard |
| TCI-W11-H | 40-10 0162 | 1 | 1 | 1 | 1 | 0 | 2 | 1 | RH Sensor 3% |
| TCI-W22 | 40-10 0075 | 2 | 1 | 0 | 2 | 0 | 2 | 1 | Schedules |
| TCI-W22-H | 40-10 0077 | 2 | 1 | 1 | 2 | 0 | 2 | 1 | RH Sensor 3% |
| TCI-W13 | 40-10 0170 | 1 | 1 | 0 | 1 | 0 | 1 | 2 | Standard |
| TCI-W13-H | 40-10 0171 | 1 | 1 | 1 | 1 | 0 | 1 | 2 | RH Sensor 3% |
| TCI-W23 | 40-10 0172 | 2 | 1 | 0 | 1 | 1 | 1 | 2 | Schedules |
| TCI-W23-H | 40-10 0173 | 2 | 1 | 1 | 1 | 1 | 1 | 2 | RH Sensor 3% |

Accessorie

| AES1-HT-A2 | 40-50 0067 | | 1 | | RH Sensor 2% |
|------------|------------|--|---|--|--------------|
| AES1-HT-A3 | 40-50 0068 | | 1 | | RH Sensor 3% |
| AES1-HT-A5 | 40-50 0069 | | 1 | | RH Sensor 5% |

Selection of actuators and sensors

Temperature sensors: Use only our approved NTC sensors to achieve maximum accuracy. Recommended is SDB-Tn10 as duct sensor, SRA-Tn10 as room sensor.

Modulating actuators: Choose actuators with an input signal type of 0...10 VDC or 4...20 mA. Minimum and maximum signal limitations may be set in software.

Binary auxiliary devices: E.g. pumps, fans, on/off valves, humidifiers, etc. Do not directly connect devices that exceed the maximum limits as described under technical data. Observe startup current on inductive loads

Jumper configuration

Jumpers are mounted vertically only.

AO - Selection of output signal type: 1

Left position: voltage output (0...10 V), factory default 0

Right position: current output (0...20 mA) 0

2. AI - Selection of input signal type:

- 0 Left position: voltage input (0...10 V), factory default
- Middle position: current input (0...20 mA)
- Right position: RT or dry-contact input 0

Mounting location

- · Install the controller on an easy accessible interior wall, approx. 1.5 m above the floor in an area of average temperature.
- · Avoid direct sunlight or other heat sources, e.g. the area above radiators and heat emitting equipment.

Avoid locations behind doors, outside walls and below or above air discharge grills and diffusers.

Location of mounting is less critical if external temperature sensors are used.

Installation

- Connect the wires to be connected to the terminals of the power case according to wiring diagram 1.
- Install the mounting plate to the flush mounting box. Make sure that the nipple with the front holding 2 screw is facing to the ground. Make sure the mounting screw heads do not stand out more than 5 mm (0.2") off the surface of the mounting plate.
- Ensure that the jumpers are set correctly 3.
- Slide the two latches located on the top of the front part into the hooks at the upper side of the 4 mounting plate.
- 5 Carefully lower the front part until the interconnector reaches the mounting-plate. Continue pressing in a gentle way until the front part is fully connected. While inserting the connectors, a slight resistance can be felt. This is normal. Do not use excessive force!
- With a Philips-type screw driver of size #2, carefully tighten the front holding screw to secure the 6. front part to the mounting plate. This screw is located on the front lower side of the unit. There is no need to tighten the screw too much.

VECTOR

Power supply

Signal inputs

Signal outputs

Environment

Technical specification

any damage caused by such a failure.

Operating voltage

Clock backup

Analog inputs

Power consumption

Electrical connection

Input signal

Resolution

Impedance emperature inputs

Resolution

Accuracy

Range

Hysteresis

Stability

Analog outputs

Relays outputs Type of disconnection

Repeatability

Output signal

Maximum load

Resolution

AC voltage

DC voltage

electronics:

Temperature

Humidity

Humidity

roduct standards

ransport & Storage

Temperature

Climatic conditions

Climatic conditions

E EMC Standard

dependent controls

Mechanical conditions

conform according to

household and similar use

EMEI Standard 73/23/EEC

Automatic electrical controls for

special requirement on temperature

between relays contacts and system

Insulation strength

Operation

Humidity sensor AES-HT-Ax:

Measuring accuracy

Range

Universal controller TCI-W13-H/TCI-W23-H

24 VAC 50/60 Hz ± 10%

vire 0.34...2.5 mm² (AWG 22...13)

RT internal, external (Sxx-Tn10 sensor)

Ext. NTC: -40...140 °C (-40...284 °F)

24 hours (Deluxe version only)

Voltage: 98kΩ current: 240Ω

Int NTC: 0 50 °C (32 122 °E)

-40...0 °C (-40...32 °F): 0.5 K

0...50 °C (32...122 °F): 0.2 K

50...100 °C (122...212 °F): 0.5 K • 100 °C (> 212 °F): 1 K

Ferminal connectors

DC.0 10V or 0 20mA

39 mV or 0.078 mA

Capacity sensor

See figure below

...100% RH

< 0.5% / yea

DC 0...10V or 0...20mA

Voltage: $\ge 5k\Omega$ current: $\le 250\Omega$

0...48 VAC, 2(1.2)A max. observe local regulations

mm (3.5" x 3.5" x 0.8")

%RH

AES-HT-A5

AES-HT-A3

AES-HT-A2

0 10 20 30 40 50 60 70 80 90 100

Figure 1: Max RH-tolerance at 25°C (77°F) ne

39 mV, 0.078 mA

Micro-interruption

To IEC 721-3-3

class 3K5

lass 2M2

EN 60730-1

EN 60730-2-9

.30 VDC, 2A max

2000VAC to EN 60730-1

0...50 °C (32...122 °F)

95%RH non-condensing

class 3K3 and class 1K3

-25...70 °C (-13...158 °F)

<95%RH non-condensing

EN 61000-6-1/ EN 6 000-6-3

o IEC 721-3-2 and IEC 721-3-1

max. 3 VA

111 112

0.1 K

1%

AO1

0.1%

Warning! This device is intended to be used for comfort applications. Where a device failure endangers human life

or detect a system failure caused by such a device failure. The manufacturer of this device cannot be held liable for

and/or property, it is the responsibility of the owner, designer and installer to add additional safety devices to prevent

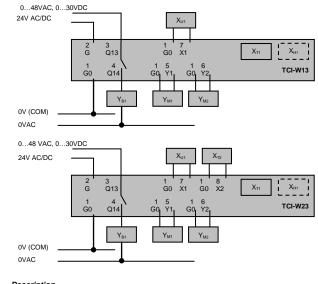
Failure to follow specifications and local regulations may endanger life, cause equipment damage and void warranty.

Wiring diagram

VECTOR

Warning: Live electrical components!

During installation, testing, servicing and troubleshooting of Vector Controls products, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.



Description G0 Power supply:

G

Xui

XT

Хн

0V, -24VDC; common for power supply, analog in- and outputs 24VAC, +24VDC NTC 10kΩ @ 25°C (77°F) or open contact,

Potential free relays contacts (see technical specification)

0...10VDC or 0...20 mA (selectable by jumper)

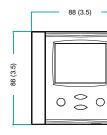
NTC 10kΩ @ 25°C (77°F) or open contact

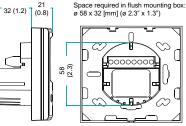
0...10 V or 0...20 mA (selectable by jumper)

21

- Power supply: Universal input
- Passive input: X_{T2}
- Binary output: Y_{B1}
- Analog outputs: Y_{M1}, X_{M2}
 - Internal temperature input
 - Internal humidity input if AES-HT is inserted

Dimensions mm (inch)





Distance for mounting screws: Horizontal and vertical: 45 to 63 [mm]

8

| Degree of pro | tection | IP30 to EN 60529 |
|-------------------|--|--|
| Pollution clas | s | II (EN 60 730-1) |
| Safety class | | II (IEC 60536) if voltage on DO > 48V III (IEC 60536) if voltage on DO < 48V |
| Overvoltage of | category | I (EN 60730-1) |
| Materials: | Cover, back part Mounting plate | Fire proof ABS plastic (UL94 class V-0) Galvanized steel |
| Dimensions (I | H x W x D) | Front part: 88 x 88 x 21 mm (3.5" x 3.5" x 0 Power case: ø 58 x 32 mm (ø 2.3" x 1.3") |
| Weight (inclue | ding package) | TCI-W13 = 253g (8.9oz) TCI-W23 = 262g (9.3 oz) |
| uption, all parar | meters and set points | %RH Relative humidity accuracy |
| | Pollution clas Safety class Overvoltage o Materials: Dimensions (I Weight (inclue | Overvoltage category Materials: Cover, back part |

Power failure

Upon power-interr are memorized in non-volatile memory, and therefore do not have to be re-entered.

Error messages

Housing

General

Err1:

- An assigned input is not enabled or missing. All control loops, functions and outputs tied to this input will be disabled. Verify input connections jumper settings and parameter settings for the input involved.
- Err3: A function refers to a disabled input Disable the function or enable the input. Err4:
- Internal failure. Product must be replaced.

±5

±4

±3

±2

+1

±0

sensor type

UI Standards

A O





Controller configuration

Proceed in the following steps in order to adapt the controller to its application:

- 1. Set jumpers for inputs and outputs
- 2. Connect power supply and inputs
- 3. Program input parameters
- 4. Program control parameters
- Program output parameters
 Test function of unit
- Test function of u
 Switch off power
- Switch off power
 Connect outputs
- Connect outputs
 Test control loop
- 10. Set user settings

Configuration parameters for firmware version 1.0

The TCI-Wx3 can be adapted to wide variety of applications. The adaptation is done with parameters. The parameters can be changed on the unit without the need of additional equipment.

Identifying the firmware version

The parameters and functionality of controller depend on its firmware revision. It is therefore important to use a matching product version and parameter set. The firmware version is marked on the package box of your product. In order to identify the firmware version of an installed controller, press UP and DOWN keys simultaneously for three seconds: The display will indicate the firmware version in the upper large digits and the revision in the lower small digits. Press the LEFT key to return to normal operation.

Changing the parameters

- Press UP and DOWN button simultaneously for three seconds. The display will indicate the firmware version in the upper large digits and the revision in the lower small digits. Press the RIGHT or POWER key to start login
- CODE is shown in small display.
- 3. The code for accessing the user parameters is 0009, for control parameters it is 0241
- 4. Select this using UP or DOWN buttons.
- 5. Press the RIGHT or POWER button after selecting the correct code.
- Once logged in the parameter group can be selected with the UP and DOWN key. Enter the group with the RIGHT or POWER key.
- 7. Once the group is selected, the parameter is displayed immediately
- Select the parameters with the UP/DOWN buttons. Change a parameter by pressing the RIGHT button. Arrows 8 to 10 show up and indicate that the parameter may be modified now. Use UP or DOWN buttons to adjust the value.
- After you are done, press RIGHT or POWER in order to save the new value of the parameter and return to the selection revel. Pressing LEFT key will discard the value and return to the selection menu without saving.
- Press the LEFT key again so as to leave the parameter menu and return to the group selection. Press LEFT key again while in the group selection to return to normal operation.
- 11. The unit will return to normal operation if no key is pressed for more than 5 minutes.

Universal controller TCI-W13-H/TCI-W23-H VECTOR

User parameters (password 09)

| Daramotor | Description | Range | Default |
|--------------------|---|---------|----------------------------|
| UP 00 | Enable access to operation modes | ON, OFF | ON |
| | | | |
| UP 01 | Enable access to set points | ON, OFF | ON |
| UP 02 | Enable manual control in cascade or fan control mode | ON, OFF | ON |
| UP 03 | Enable change of heating/cooling mode for 2 pipe systems | ON, OFF | ON |
| UP 04 | Enable access to time programs: | ON, OFF | ON |
| UP 05 | State after power failure: 0= off, 1= on, 2= state before power failure | 0, 1, 2 | 2 |
| UP 06 | Enable economy (unoccupied) mode. Shift the set point to a lower temperature in winter or higher temperature in summer in order to save energy. Economy mode may be activated through the POWER button, or with the external input (typically for key card switches in hotel rooms or motion detectors for meeting rooms.) | ON, OFF | OFF |
| UP 07 | Celsius or Fahrenheit: ON= Fahrenheit, OFF= Celsius | ON, OFF | OFF (Celsius) |
| UP 08 | Show standard display while no key is pressed | ON, OFF | ON |
| UP 09 | Select contents of large LCD display in standard mode: 00 = OFF 03 = Analog output 01 = Input 04 = Binary output 02 = Set point 05 = Clock | 05 | 1 |
| UP 10 | Select ID of contents of upper digit display Input: Set point: Analog or Binary output: 1= 1T 1= Lp1 floating output: 1 = DO1 2= 1H 2= Lp2 1 = AO1 2 = AO2 3= 1U 2 = AO2 2 = AO2 1 | 04 | 2 |
| UP 11 | Select contents of lower digit display in standard mode | 05 | TCI-W13 = 2 TCI-W23 = 5 |
| UP 12 | Select ID of contents of lower digit display | 04 | 1 |
| UP 13 | Select analog output for display in vertical bar 00 = OFF 01 = AO1 02 = AO2 03 = Output lp1 04 = Output lp2 | 04 | 3 |
| UP 14 | Display heating/cooling state in standard display mode | ON, OFF | OFF |
| UP 15 | ON = Alarms blink after being active and need to be confirmed OFF= Alarms are only shown when they are active | ON, OFF | ON |
| UP 16 (TCI-W23) | Clock display type: OFF = 24-hr, ON = 12-hr (AM/PM) | ON, OFF | OFF |
| UP 17 (TCI-W23) | Reset timer for manual override of time schedule: 0= Not active 255— delay in minutes in case the controller is manually switched on in scheduled off or economy mode. The controller will return to scheduled function after expiration of this delay. | 0255 | 60 (min) |

Control parameters (password 241)

Warning! Only experts should change these settings! The parameters are grouped according to control modules. After completing the logging in, a control module must be selected before accessing the parameters.

| N | Nodule | Description |
|---|---------------|---------------------------------------|
| L | JI | Input configuration: 1T, 1H, 1U, 2T |
| L | P | Control loops Lp1, Lp2 |
| F | 10 | Analog output configuration, AO1, AO2 |
| E | 00 | Binary output configuration, do1 |
| F | Ū | Special functions |

Internal input configuration (TI1)

| Parameter | Description | Range | Standard |
|-----------|--|-----------|--------------|
| 1t 00 | Enable internal sensor | ON, OFF | OFF |
| 1t 01 | Display minimum value | -50205 | 0 |
| 1t 02 | Display maximum value | -50205 | 100 |
| 1t 03 | Sensor sampling rate(control speed decrease as rate increases) | 0100 | 10 |
| 1t 04 | Sensor calibration | -10.010.0 | 0 |
| 1t 05 | Alarm 1 low limit (1T), alarm 3 low limit (1H) | OFF, ON | OFF |
| 1t 06 | Alarm 1/3 low limit values | -50205 °C | 5°C (41°F) |
| 1t 07 | Alarm 2high limit (1T), alarm 4high limit (1H) | OFF, ON | OFF |
| 1t 08 | Alarm 2/4 high limit values | -50205 °C | 50°C (122°F) |
| 1t 09 | Hysteresis alarm 1, 2, 3, 4 | 0100 °C | 5°C (10°F) |
| 1t 10 | Calculate a range of inputs (0= not active): 1= average, 2= minimum, 3= maximum | 03 | 0 |

Internal input configuration (HI1)

| Parameter | Description | Range | Standard |
|-----------|--|-----------|----------|
| 1H00 | Enable internal sensor | ON, OFF | ON |
| 1H01 | Display minimum value | -50205 | 0 |
| 1H02 | Display maximum value | -50205 | 100 |
| 1H03 | Sensor sampling rate(control speed decrease as rate increases) | 0100 | 10 |
| 1H04 | Sensor calibration | -10.010.0 | 0 |
| 1H05 | Alarm 1 low limit (1T), alarm 3 low limit (1H) | OFF, ON | OFF |
| 1H06 | Alarm 1/3 low limit values | 0100% | 5% |
| 1H07 | Alarm 2high limit (1T), alarm 4high limit (1H) | OFF, ON | OFF |
| 1H08 | Alarm 2/4 high limit values | 0100% | 95% |
| 1H09 | Hysteresis alarm 1, 2, 3, 4 | 0100% | 5% |
| 1H10 | Calculate a range of inputs (0= not active): 1= average, 2= minimum, 3= maximum | 03 | 0 |

External input configuration (UI1, TI2)

| Parar | neter | Description | Range | Standard |
|-------|-------|--|-----------|--------------|
| 1u 00 | 2t 00 | Signal type (0= not active): 1= 010V or 020mA or open contact, 2= 210 V or 420 mA, 3= NTC temperature sensor | 03 | 0 |
| 1u 01 | 2t 01 | Display minimum value | -50205 | 0 |
| 1u 02 | 2t 02 | Display maximum value | -50205 | 100 |
| 1u 03 | 2t 03 | Analog input display range: 0 = x0.1, 1 = x1, 2 = x10, 3 = x100 | 02 | 1 |
| 1u 04 | 2t 04 | Analog input unit of measure: 0= no unit, 1= %, 2= °C /°F, 3= Pa | 03 | 2 |
| 1u 05 | 2t 05 | Sensor sampling rate (control speed decrease as rate increases) | 0100 | 10 |
| 1u 06 | 2t 06 | Sensor calibration | Range dep | 0 |
| 1u 07 | 2t 07 | Alarm 5 low limit (1u), alarm 7 low limit (2t) | OFF, ON | OFF |
| 1u 08 | 2t 08 | Alarm 5 low limit value (1u), alarm 7 low limit value (2t) | -50205 °C | 5°C (41°F) |
| 1u 09 | 2t 09 | Alarm 6 high limit (1u), alarm 8 high limit (2t) | OFF, ON | OFF |
| 1u 10 | 2t 10 | Alarm 6 high limit value 1u), alarm 8 high limit value (2t) | -50205 °C | 50°C (122°F) |
| 1u 11 | 2t 11 | Hysteresis alarm 5 and 6 (1u), alarms 7 and 8 (2t) | 0100 °C | 5°C (10°F) |
| 1u 12 | 2t 12 | Calculate a range of inputs (0=not active): 1= average, 2= minimum, 3= maximum, 4= differential | 04 | 0 |

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Universal controller TCI-W13-H/TCI-W23-H



Universal controller TCI-W13-H/TCI-W23-H

| ramete | Description | Range | Standard |
|--------|---|-----------|----------|
| 1L 00 | Select loop control input (0= loop disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2T | 04 | 2 |
| 1L 01 | Minimum set point limit heating | per input | 10% |
| 1L 02 | Maximum set point limit heating | per input | 90% |
| 1L 03 | Minimum set point limit cooling | per input | 10% |
| 1L 04 | Maximum set point limit cooling | per input | 90% |
| 1L 05 | Enable set point compensation (0= disabled) 1= winter compensation, 2= summer compensation, 3= winter and summer | 03 | 0 |
| 1L 06 | Loop input special (0= normal): 1= combine loop 1 and loop 2 2= cascade with reverse sequence of primary loop 3= cascade with direct sequence primary loop 4= cascade with both reverse and direct sequence of primary loop | 04 | 0 |
| 1L 07 | Economy mode set point shift: (Function depends on 1L25) The comfort (occupied) set point is shifted by the value set with parameter. Reduces the heating set point and increases the cooling set point. | per input | 10% |
| 1L 08 | Dead zone between heating and cooling set points The dead zone span lies between the heating and the cooling set point. The output is off while the measured value is within the dead zone span. A negative dead zone is not possible. | per input | 5% |
| 1L 09 | Offset for heating PI sequence | per input | 0 |
| 1L 10 | Offset for cooling PI sequence | per input | 0 |
| 1L 11 | P-band heating | per input | 10% |
| 1L 12 | P-band cooling | per input | 10% |
| | Integral gain heating (0.1 steps) | | |
| 1L 13 | low= slow reaction, high= fast reaction | 025.5 | 0.0 |
| 1L 14 | Integral gain cooling (0.1 steps) | 025.5 | 0.0 |
| 1L 15 | Measuring interval integral (seconds) low= fast reaction, high value= slow reaction | 0255 | 1 |
| 1L 16 | Action of stages: 0= cumulative: stage 1 stays on when 2 on comes on 1= single: stage 1 turns off when 2 on comes on 2= digital: stage 1 only, stage 2 only, then stage 1 plus 2 | 02 | 0 |
| 1L 17 | Offset for heating/reverse binary sequences | per input | 0% |
| 1L 18 | Offset for cooling/direct binary sequences | per input | 0% |
| 1L 19 | Switching span heating | per input | 10% |
| 1L 20 | Switching span cooling | per input | 10% |
| 1L 21 | Switching hysteresis | per input | 5% |
| 1L 22 | Switching delay | 0255s | 30s |
| 1L 23 | Activation of reverse/direct (heat/cool) sequence OFF= activates based on demand ON = follows heat/cool state of controller | ON/OFF | OFF |
| 1L 24 | Delay for heat /cool changeover when L23=OFF | 0255 min | 5 min |
| 1L 25 | Fixed set point in standby mode | 5200 mm | 0 1111 |
| 1L 25 | OFF = Standby set point in standby mode OFF = Standby set point shift applies ON = In standby mode use minimum set point limit as set point in heating mode or maximum set point limit in cooling mode | ON, OFF | OFF |
| 1L 26 | Set point compensation range, the maximum range the set point is shifted. 0 = Temperature setback: the set point is shifted towards set point limit | Acc input | 0.0 °C |

| Parameter | Description | Range | Standard |
|-----------|---|-----------|-------------|
| 2L 00 | Select loop control input (0= loop disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2T | 04 | 0 |
| 2L 01 | Minimum set point limit heating | per input | 10°C(50°F |
| 2L 02 | Maximum set point limit heating | per input | 28°C(82°F |
| 2L 03 | Minimum set point limit cooling | per input | 18°C(64°F |
| 2L 04 | Maximum set point limit cooling | per input | 34°C(93°F |
| 2L 05 | Enable set point compensation (0= disabled) 1= winter compensation, 2= summer compensation, 3= winter and summer | 03 | 0 |
| 2L 06 | Loop input special (0= normal): 1= combine loop 1 and loop 2 2= cascade with reverse sequence of primary loop 3= cascade with direct sequence primary loop 4= cascade with both reverse and direct sequence of primary loop | 04 | 0 |
| 2L 07 | Economy mode set point shift: (Function depends on 2L25) The comfort (occupied) set point is shifted by the value set with parameter. Reduces the heating set point and increases the cooling set point. | per input | 5.0°C(10°F |
| 2L 08 | Dead zone between heating and cooling set points The dead zone span lies between the heating and the cooling set point. The output is off while the measured value is within the dead zone span. A negative dead zone is not possible. | per input | 1.0°C (2°F |
| 2L 09 | Offset for heating PI sequence | per input | 0 |
| 2L 10 | Offset for cooling PI sequence | per input | 0 |
| 2L 11 | P-band heating | per input | 2.0°C(4.0°F |
| 2L 12 | P-band cooling | per input | 2.0°C (4.0° |
| 2L 13 | Integral gain heating (0.1 steps) low= slow reaction, high= fast reaction | 025.5 | 0.0 |
| 2L 14 | Integral gain cooling (0.1 steps) | 025.5 | 0.0 |
| 2L 15 | Measuring interval integral (seconds) low= fast reaction, high value= slow reaction | 0255 | 1 |
| 2L 16 | Action of stages: 0= cumulative: stage 1 stays on when 2 on comes on 1= single: stage 1 turns off when 2 on comes on 2= digital: stage 1 only, stage 2 only, then stage 1 plus 2 | 02 | 0 |
| 2L 17 | Offset for heating/reverse binary sequences | per input | 0.0°C (0.0° |
| 2L 18 | Offset for cooling/direct binary sequences | per input | 0.0°C (0.0° |
| 2L 19 | Switching span heating | per input | 1.0°C (2.0° |
| 2L 20 | Switching span cooling | per input | 1.0°C (2.0° |
| 2L 21 | Switching hysteresis | per input | 0.5°C (1.0° |
| 21 22 | Switching delay | 0255s | 10s |
| 2L 23 | Activation of reverse/direct (heat/cool) sequence OFF= activates based on demand ON = follows heat/cool state of controller | ON, OFF | OFF |
| 2L 24 | Delay for heat /cool changeover when L23=OFF | 0255 min | 5 min |
| 2L 25 | Fixed set point in standby mode OFF = Standby set point shift applies ON = In standby mode use minimum set point limit as set point in heating mode or maximum set point limit in cooling mode | ON, OFF | OFF |
| 2L 26 | Set point compensation range, the maximum range the set point is shifted. 0 = Temperature setback: the set point is shifted towards set point limit | Acc input | 0.0°C |

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VECTOR

| Parameter | Description | Range | Standard |
|-----------|--|-----------|--------------------------|
| 1A 00 | Select control loop or special function (0= OFF): 1 = LP1, 2 = LP2 3 = Dehumidify (4 pipe, max LP1 cooling, LP2 direct) 4 = Manual positioning or time schedule controlled (0100%) 5 = Transmit value of an input | 05 | 1 |
| 1A 01 | When 1A00=1 configure output: 0= Heating/reverse 1= Cooling/direct 2= Heating and cooling (2 pipe) 3= Transmit set point When 1A00 = 4 manual positioning or time schedule controlled 0 = Time schedule controlled only 1 = Manual positioning and time schedule controlled | 04 | 0 |
| | When 1A00=5, select input (0= function disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2T | | |
| 1A 02 | Type of output signal: OFF= 010V, 020mA, ON= 210V, 420mA | ON, OFF | OFF (010V, 020 mA) |
| 1A 03 | Minimum limitation of output signal default and in loop heating mode | 0100% | 0 |
| 1A 04 | Maximum limitation of output signal default and in loop heating mode | 0100% | 100% |
| 1A 05 | Minimum limitation of output signal in loop cooling mode | 0100% | 0% |
| 1A 06 | Maximum limitation of output signal in loop cooling mode | 0100% | 100% |
| 1A 07 | Choose alarm to set output to 100% (output 0% on conflicting alarms) | Selection | ~~~~~~~~ |
| 1A 08 | Choose alarm to set output to 0%. (output 0% on conflicting alarms) | Selection | ~~~~~~~ |
| 1A 09 | Transmit value (1A00=5): minimum input value | Acc input | - |
| 1A 10 | Transmit value (1A00=5): maximum input value | Acc input | - |

| Binar | y output – binary control | | |
|-----------|---|-----------|----------|
| Parameter | | Range | Standard |
| 1d 00 | Enable digital or PWM output OFF= 1d is a digital output ON = 1d is a PWM output | ON, OFF | OFF |
| 1d 01 | Select control loop or special function (0= OFF) 1= LP1 2= LP2 3= Dehumidify (4 pipe, max LP1 cooling, LP2 direct) 4= Manual positioning (on/off) 5= State functions | 05 | 0 |
| 1d 02 | When 1d01=1, configure output: 0= Stage 1 heating/reverse 1= Stage 1 heating/reverse 2= Stage 1 heating/reverse 4= Stage 2 heating/reverse 4= Stage 2 heating and cooling, reverse and direct 5= Stage 2 heating reverse 4= Stage 2 heating and cooling, reverse and direct 1f 1d01 = 4 Manual positioning or time schedule controlled 0 = time schedule controlled only 1 = manual positioning and time schedule controlled When 1d01-5, select statet functions: 0= ON if controller operation state is ON 1= ON while odemand on any output 2= ON while controller in heating mode and operation state ON 3= ON while controller in cooling mode and operation state ON | 05 | 0 |
| 1d 03 | Switch-off delay (time output active with no more demand) Delay is in seconds or minutes depending on d09 | 0255s | 90s |
| 1d 04 | Switch-on delay (time demand active before output on) In state mode 1d01=5 outputs disabled during switch-on delay Delay is in seconds or minutes depending on d09 | 0255s | 5s |
| 1d 05 | Activate PWM, set cycle time, seconds (>0 activates, 0 deactivates) | 01275 | 0 |
| 1d 06 | Choose alarm to set output to ON (output OFF on conflicting alarms) | Selection | ~~~~~~~ |
| 1d 07 | Choose alarm to set output to OFF (output OFF on conflicting alarms) ♡ ♡ ♡ ♡ ♡ ♡ ♡ ♡ Alarm: 1 2 3 4 5 6 7 8 | Selection | ~~~~~~ |
| 1d 08 | Display fan symbol while active | ON, OFF | OFF |
| 1d 09 | Binary switching delays in minutes or seconds OFF = delays are in seconds, ON = delays are in minutes | ON, OFF | OFF |

VECTOR Universal controller TCI-W13-H/TCI-W23-H

Universal controller TCI-W13-H/TCI-W23-H

| Parameter | Description | Range | Standard |
|-----------|--|-----------------|----------|
| Fu 00 | Select compensation input (0= function disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2T | 04 | 0 |
| Fu 01 | Winter compensation set point setback OFF= shift toward control loop heating set point minimum ON= shift toward control loop heating set point maximum | ON, OFF | OFF |
| Fu 02 | Winter compensation lower limit value – end shift | Range acc input | 5°C |
| Fu 03 | Winter compensation upper limit value – start shift | Range acc input | 20°C |
| Fu 04 | Summer compensation set point setback OFF= shift toward control loop cooling set point minimum ON= shift toward control loop cooling set point maximum | ON, OFF | ON |
| Fu 05 | Summer compensation lower limit value – start shift | Range acc input | 35°C |
| Fu 06 | Summer compensation upper limit value – end shift | Range acc input | 40°C |
| Fu 07 | Show hot/cool symbol while compensation active | ON, OFF | OFF |
| Special f | unctions – remote control comfort – economy | | |
| Fu 08 | Select comfort/economy changeover input (0= disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2T | 04 | 0 |
| Fu 09 | Economy activation delay (seconds) | 01275 | 300 |
| Fu 10 | Input limit 1 | Range acc input | 10 |
| Fu 11 | Input limit 2 | Range acc input | 90 |
| | unctions – remote control enable – disable | | |
| Fu 12 | Select enable-disable input (0=function disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2T | 04 | 0 |
| FU 13 | Manual override permitted (without waiting for delay). This function allows starting the controller; although the enable conditions are not met. The controller will switch off again if the running conditions are not met until the disable delay is expired. | ON, OFF | OFF |
| Fu 14 | Enable delay (seconds) | 01275 | 0 |
| Fu 15 | Disable delay (seconds) | 01275 | 300 |
| Fu 16 | Range of limits: OFF = When limit 2 is greater than limit 1, enable when input value is greater than limit 2, disable when input value is less than limit 1, When limit 2 is less than limit 1, enable when input value less than limit 1, disable when input value is greater than limit 2. ON = When limit 2 is greater than limit 1 enable when input value is between limit 1 and limit 2. When limit 2 is less than limit 1, enable when input value below limit 2 or above limit 1 | ON, OFF | OFF |
| Fu 17 | Input limit 1 | Range acc input | 10 |
| Fu 18 | Input limit 2 | Range acc input | 90 |
| Fu 19 | Disable in case of alarms | Selection | |
| | unctions – Remote heat / cool (reverse / direct) | | |
| | , , , | liange | |
| Fu 20 | Select heat/cool changeover input (0=function disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2T, 5= h/c status loop 1, 6= h/c status loop 2 | 06 | 0 |
| E 04 | O self second self sectors (second s) | | |

Fu 21 Cooling activation delay (seconds)

Fu 22 Input limit 1

Fu 23 Input limit 2

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0...1275

Range acc input

Range acc input

300

20

40