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## TCI-W13, TCI-W23-W50 wall mounted universal controller

#### General description

The TCI-W is a stand-alone wall mounted electronic universal controller with two autonomous control loops. Each control loop may use up to 2 PID sequences and 6 binary sequences. The TCI-W13 features 1 independent control loop, 1 universal input, 1 binary relay output and 2 analog outputs, the TCI-W23 offers 2 independent control loops, 1 universal inputs, 1 passive input, 1 binary relay output and 2 analog output. A detailed configuration is possible by following a simple setup routine. The TCI can be configured using the standard operation terminal. No special tool or software is required.

#### Ordering, name convention

TCI-W23-U	Optional Functions an	nd housing
	Housing:	U = 2 x 4" type housing, Blank = square housing
└	In/Outputs:	13 = 1UI, 1DOR, 2AO, 23 = 1UI, 1Passive In, 1DOR, 2AO
[	Control loops:	13 = 1 control loop, 23 = 2 control loops
L	Mounting:	W = Wall mounted
i	Series Indication:	TCI

Item code	Loop	temperature	humidity	UI	TI	relays	AO	Option
40-10 0073	1	1	0	1	0	2	1	Standard
40-10 0162	1	1	1	1	0	2	1	RH Sensor 3%
40-10 0075	2	1	0	2	0	2	1	Schedules
40-10 0077	2	1	1	2	0	2	1	RH Sensor 3%
40-10 0170	1	1	0	1	0	1	2	Standard
40-10 0171	1	1	1	1	0	1	2	RH Sensor 3%
40-10 0172	2	1	0	1	1	1	2	Schedules
40-10 0173	2	1	1	1	1	1	2	RH Sensor 3%
	40-10 0162 40-10 0075 40-10 0077 40-10 0170 40-10 0171 40-10 0172	40-10         0162         1           40-10         0075         2           40-10         0077         2           40-10         0170         1           40-10         0171         1           40-10         0172         2	40-10 0073         1         1           40-10 0162         1         1           40-10 0075         2         1           40-10 0077         2         1           40-10 0077         1         1           40-10 0170         1         1           40-10 0171         1         1           40-10 0172         2         1	40-10 0073         1         1         0           40-10 0162         1         1         1           40-10 0075         2         1         0           40-10 0077         2         1         1           40-10 0077         2         1         1           40-10 0077         1         1         0           40-10 0170         1         1         1           40-10 0171         1         1         1	40-10 0073         1         1         0         1           40-10 0162         1         1         1         1         1           40-10 0162         1         1         1         1         1         1           40-10 0075         2         1         0         2         1         1         2           40-10 0077         2         1         1         0         1         1         0         1           40-10 0170         1         1         0         1         1         1         1         1         1           40-10 0171         1 </td <td></td> <td></td> <td></td>			

#### Accessories

AES1-HT-A2	40-50 0067		1		RH Sensor 2%
AES1-HT-A3	40-50 0068		1		RH Sensor 3%
AES1-HT-A5	40-50 0069		1		RH Sensor 5%

#### Selection of actuators and sensors

Temperature sensors: Use only our approved NTC sensors to achieve maximum accuracy. Recommended is SDB-Tn10 as duct sensor, SRA-Tn10 as room sensor

Modulating actuators: Choose actuators with an input signal type of 0...10 VDC or 4...20 mA. Minimum and maximum signal limitations may be set in software.

Binary auxiliary devices: E.g. pumps, fans, on/off valves, humidifiers, etc. Do not directly connect devices that exceed the maximum limits as described under technical data. Observe startup current on inductive

#### Jumper configuration

#### Jumpers are mounted vertically only.

- AO Selection of output signal type:
  - Left position: voltage output (0...10 V), factory default
  - Right position: current output (0...20 mA)
- AI Selection of input signal type: 2
  - Left position: voltage input (0...10 V), factory default 0
  - Middle position: current input (0...20 mA) 0
  - Right position: RT or dry-contact input 0

#### Mounting location

- · Install the controller on an easy accessible interior wall, approx. 1.5 m above the floor in an area of average temperature
- Avoid direct sunlight or other heat sources, e.g. the area above radiators and heat emitting equipment. · Avoid locations behind doors, outside walls and below or above air discharge grills and diffusers
- · Location of mounting is less critical if external temperature sensors are used

Installation

- Connect the wires to be connected to the terminals of the power case according to wiring diagram 1
- Install the mounting plate to the flush mounting box. Make sure that the nipple with the front holding 2. screw is facing to the ground. Make sure the mounting screw heads do not stand out more than 5 mm (0.2") off the surface of the mounting plate
- 3. Ensure that the jumpers are set correctly
- Slide the two latches located on the top of the front part into the hooks at the upper side of the Δ mounting plate
- Carefully lower the front part until the interconnector reaches the mounting-plate. Continue 5. pressing in a gentle way until the front part is fully connected. While inserting the connectors, a slight resistance can be felt. This is normal. Do not use excessive force!
- With a Philips-type screw driver of size #2, carefully tighten the front holding screw to secure the 6 front part to the mounting plate. This screw is located on the front lower side of the unit. There is no need to tighten the screw too much

# VECTOR

Power supply

Signal inputs

Signal outputs

Environment

Standards

Housing

General

Err3:

Err4:

Power failure

Error messages

do not have to be re-entered

**Technical specification** 

any damage caused by such a failure.

Operating voltage

Clock backup

Analog inputs

Power consumption

lectrical connection

Input signal

Resolution

Impedance

emperature inputs

Resolution

Accuracy

Range Measuring accuracy

Stability

nalog outputs

Relays outputs

Hysteresis

Repeatability

Output signal Resolution

Maximum load

AC Voltage

DC Voltage

electronics

Temperature

Temperature

Humidity

Humidity

Product standards

Degree of protection

Overvoltage category

imensions (H x W x D)

Weight (including package

All control loops, functions and outputs tied to

connections, jumper settings and parameter

A function refers to a disabled input. Disable the function or enable the input.

Internal failure. Product must be replaced.

Pollution class

Safety class

Materials:

Upon power-interruption, all parameters and set points

are memorized in non-volatile memory, and therefore

Err1: An assigned input is not enabled or missing.

settings for the input involved.

this input will be disabled. Verify input

ransport & storage

Climatic conditions

Climatic conditions

EMC Standard

Mechanical conditions

conform according to

household and similar use

dependent controls

EMEI Standard 73/23/EEC

Automatic electrical controls for

Special requirement on temperature

Cover, back part

Mounting plate

sulation strength

Operation

Type of disconnection

between relays contacts and system

between neighboring contacts

Humidity sensor AES-HT-Ax:

Range

# Universal controller TCI-W13/23-W50

24 VAC ±10%, 50/60 Hz, Class 2, 48 VA max.

Warning! This device is intended to be used for comfort applications. Where a device failure endangers human life

or detect a system failure caused by such a device failure. The manufacturer of this device cannot be held liable for

and/or property, it is the responsibility of the owner, designer and installer to add additional safety devices to prevent

Failure to follow specifications and local regulations may endanger life, cause equipment damage and void warranty.

24 VDC ±10%

Ferminal connectors. wire 0.34...2.5 mm<sup>2</sup> (AWG 22...13) 24 hours (TCI-W22 only)

UI1, UI2 DC 0...10V or 0...20mA

Voltage: 98kQ current: 240Q

Int. NTC: 0...50 °C (32...122 °F)

-40...0 °C (-40...32 °F): 0.5 K

0...50 °C (32...122 °F): 0.2 K 50...100 °C (122...212 °F): 0.5 K

100 °C (>212 °F): 1 K

DC.0 10V or 0 20mA

2000 VAC to EN 60730-1

1250 VAC to EN 60730-1

)...50 °C (32...122 °F)

<95% RH non-condensing

class 3K3 and class 1K3

-25 70 °C (-13 158 °F)

<95% RH non-condensing

EN 61000-6-1/ EN 61000-6-3

To EN 60721-3-2 and EN 60721-3-1

Voltage: ≥5 kΩ current: ≤250Ω

39 mV, 0.078 mA

Micro-interruption

To EN 60721-3-3

class 3K5

lass 2M2

EN 60730-1

EN 60730-2-9

IP30 to EN 60529

II (EN 60730-1)

L (EN 60730-1)

Galvanized steel

FCI-W13 = 253g (8.9oz) TCI-W23 = 262g (9.3 gz)

Capacity sensor

See figure below

< 0.5% / vear

DO1, DO2

RT internal external (Sxx-Tn10 sensor)

Ext. NTC: -40...140 °C (-40...284 °F)

39 mV or 0 078 mA

max. 3 VA

01K

± 1%

+ 0.1%

AO

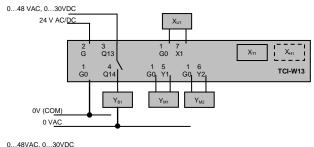
#### Universal controller TCI-W13/23-W50

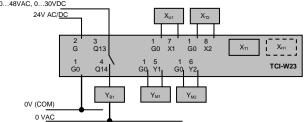
## Wiring diagram

VECTOR

#### Warning: Live electrical components!

During installation, testing, servicing and troubleshooting of Vector Controls products, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.





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#### Description G0 Powe

G

Xui

Y<sub>M1</sub>

Y<sub>M2</sub>

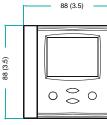
**X**<sub>T1</sub>

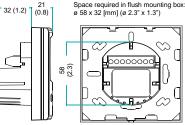
XHI

Power supply:	0V, -24VDC; common for power supply, analog in- and outputs
Power supply:	24VAC, +24VDC
Universal input:	NTC 10kΩ @ 25°C (77°F) or open contact,
	010VDC or 020 mA (selectable by jumper)
Dessive input:	NTC 10k0 @ 25°C (77°E) or open contact

- X<sub>T2</sub> Passive input Y<sub>B1</sub> Binary output:
  - Analog output:
  - Analog outputs:
  - Internal temperature input

#### Dimensions mm (inch)





Distance for mounting screws Horizontal and vertical: 45 to 63 [mm]

%RH▲ Relative humidity accuracy ±5 ±4 AES-HT-A5 +3 AES-HT-A3 ±2 AES-HT-A2 ±1 +00 10 20 30 40 50 60 70 80 90 100 Figure 1: Max RH-tolerance at 25°C (77°F) per %RH

I (IEC 60536) if voltage on DO > 48V

II (IEC 60536) if voltage on DO < 48V

Fire proof ABS plastic (UL94 class V-0)

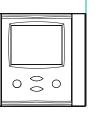
Power case: ø 58 x 32 mm (ø 2.3" x 1.3")

Front part: 88 x 88 x 21 mm (3.5" x 3.5" x 0.8")

Doc: 70-00-0381A-50 V1 0 20160523

NTC 10kΩ @ 25°C (77°F) or open contact Potential free relays contacts (see technical specification) 0...10 V or 0...20 mA 2-pipe VAV control

- 0...10 V or 0...20 mA Heating control reheat.
- Internal humidity input if AES-HT is inserted







## Universal controller TCI-W13/23-W50

### **Controller configuration**

Proceed in the following steps in order to adapt the controller to its application:

- 1. Set jumpers for inputs and outputs
- 2. Connect power supply and inputs
- 3. Program input parameters
- 4. Program control parameters
- Program output parameters
   Test function of unit
- Test function of u
   Switch off power
- Switch off power
   Connect outputs
- Connect outputs
   Test control loop
- 10. Set user settings

#### Configuration parameters for firmware version 1.0-W50

The TCI-Wx3 can be adapted to wide variety of applications. The adaptation is done with parameters. The parameters can be changed on the unit without the need of additional equipment.

#### Identifying the firmware version

The parameters and functionality of controller depend on its firmware revision. It is therefore important to use a matching product version and parameter set. The firmware version is marked on the package box of your product. In order to identify the firmware version of an installed controller, press UP and DOWN keys simultaneously for three seconds: The display will indicate the firmware version in the upper large digits and the revision in the lower small digits. Press the LEFT key to return to normal operation.

#### Changing the parameters

- Press UP and DOWN button simultaneously for three seconds. The display will indicate the firmware version in the upper large digits and the revision in the lower small digits. Press the RIGHT or POWER key to start login
- 2. CODE is shown in small display
- 3. The code for accessing the user parameters is 0009, for control parameters it is 0241
- 4. Select this using UP or DOWN buttons
- 5. Press the RIGHT or POWER button after selecting the correct code
- Once logged in the parameter group can be selected with the UP and DOWN key. Enter the group with the RIGHT or POWER key
- 7. Once the group is selected, the parameter is displayed immediately
- Select the parameters with the UP/DOWN buttons. Change a parameter by pressing the RIGHT button. Arrows 8 to 10 show up and indicate that the parameter may be modified now. Use UP or DOWN buttons to adjust the value
- After you are done, press RIGHT or POWER in order to save the new value of the parameter and return to the selection revel. Pressing LEFT key will discard the value and return to the selection menu without saving
- Press the LEFT key again so as to leave the parameter menu and return to the group selection. Press LEFT key again while in the group selection to return to normal operation
- 11. The unit will return to normal operation if no key is pressed for more than 5 minutes



# User parameters (password 09)

Parameter	Description				Range	Default
UP 00	Enable access	to operation m	odes		ON, OFF	ON
UP 01	Enable access	to set points			ON, OFF	ON
UP 02	Enable manual	control in case	cade or fan control r	node	ON, OFF	ON
UP 03	Enable change	of heating/cod	ling mode for 2 pipe	e systems	ON, OFF	ON
UP 04	Enable access	to time program		ON, OFF	ON	
UP 05	State after pow	ver failure:			0, 1, 2	2
	0= off, 1= on,	2= state before				
UP 06	Enable econon				ON, OFF	ON
			emperature in winte			
			er to save energy. E			
			POWER button, or			
	detectors for m		vitches in hotel room	is or motion		
UP 07			ahrenheit, OFF= C	oleiue	ON, OFF	OFF (Celsius)
UP 08			no key is pressed	010100	ON, OFF	OFF (Ceisius) ON
UP 09			display in standard i	mode:	05	1
51 05	00 = OFF	S S. large LOD	03 = Analog out		00	· ·
	01 = Input		04 = Binary out			1
	02 = Set point		05 = Clock			
UP 10	Select ID of co	ntents of upper			04	1
	Input:	Set point:	Analog or	Binary output:		
	1= 1T	1= Lp1	floating output:	1DO1		
	2=1H	2= Lp2	1 = AO1			
	3= 1U		2 = AO2			
	4= 2T					-
UP 11	Select contents	s of lower digit	display in standard	mode	05	TCI-W13 = 2 TCI-W23 = 5
UP 12	Calant ID of an		dicit dice less		0.4	
UP 12	Select ID of co Select analog of		04	1		
UF 13	00 = OFF	Jurpur IOI ulspia	04	3		
	00 = OFF 01 = AO1					
	02 = AO2					
	03 = Output lp1	1				
	04 = Output Ip2			1		
UP 14	Display heating	cooling state	in standard display	mode	ON, OFF	OFF
UP 15			active and need to		ON, OFF	ON
			when they are acti		. ,	
UP 16					ON, OFF	OFF
(TCI-W23)	. , ,		-hr, ON= 12-hr(AN	,		<u> </u>
UP 17		manual overrid	de of time schedule:		0255	60 (min)
(TCI-W23)	0=Not active					
			case the controller is			
			or economy mode. 1			
	return to sched	luied function a	fter expiration of thi	s delay.		



### Universal controller TCI-W13/23-W50

### Control parameters (password 241)

Warning! Only experts should change these settings! The parameters are grouped according to control modules. After completing the logging in, a control module must be selected before accessing the parameters.

Module	Description

Module	Description
UI	Input configuration: 1T, 1H, 1U, 2T
LP	Control loops Lp1, Lp2
AO	Analog output configuration, AO1, AO2
DO	Binary output configuration, do1
FU	Special functions

Parameter	Description	Range	Standar
1t 00	Enable internal sensor	ON, OFF	ON
1t 01	Display minimum value	-50205	0
1t 02	Display maximum value	-50205	100
1t 03	Sensor sampling rate(control speed decrease as rate increases)	0100	10
1t 04	Sensor calibration	-10.010.0	0
1t 05	Alarm 1 low limit	OFF, ON	OFF
1t 06	Alarm 1/3 low limit values	-50205 °C	5°C (41°
1t 07	Alarm 2high limit	OFF, ON	OFF
1t 08	Alarm 2/4 high limit values	-50205 °C	50°C (122
1t 09	Hysteresis alarm 1, 2	0100 °C	5°C (10°
1t 10	Calculate a range of inputs (0= not active):	03	0
11 10	1= average, 2= minimum, 3= maximum	00	-
nternal in	1= average, 2= minimum, 3= maximum		-
nternal in Parameter	1= average, 2= minimum, 3= maximum	Range	Standar
nternal in Parameter 1H 00	1= average, 2= minimum, 3= maximum	Range ON, OFF	OFF
nternal in Parameter 1H 00 1H01	1= average, 2= minimum, 3= maximum aput configuration (HI1) Description	Range           ON, OFF           -50205	OFF 0
nternal in Parameter 1H 00	1= average, 2= minimum, 3= maximum aput configuration (HI1) Description Enable internal sensor Display maximum value Display maximum value	Range ON, OFF -50205 -50205	OFF
nternal in Parameter 1H 00 1H01 1H02 1H03	1= average, 2= minimum, 3= maximum put configuration (H11) Description Enable internal sensor Display minimum value Display maximum value Sensor sampling rate(control speed decrease as rate increases)	Range ON, OFF -50205 -50205 0100	OFF 0
nternal in Parameter 1H 00 1H01 1H02	1= average, 2= minimum, 3= maximum aput configuration (HI1) Description Enable internal sensor Display maximum value Display maximum value	Range ON, OFF -50205 -50205	OFF 0 100
nternal in Parameter 1H 00 1H01 1H02 1H03	1= average, 2= minimum, 3= maximum put configuration (H11) Description Enable internal sensor Display minimum value Display maximum value Sensor sampling rate(control speed decrease as rate increases)	Range ON, OFF -50205 -50205 0100	OFF 0 100 10
<b>nternal in</b> Parameter 1H 00 1H01 1H02 1H03 1H04	1= average, 2= minimum, 3= maximum put configuration (H11) Description Enable internal sensor Display maximum value Display maximum value Sensor sampling rate(control speed decrease as rate increases) Sensor calibration	Range           ON, OFF           -50205           -50205           0100           -10.010.0	OFF 0 100 10 0
nternal in Parameter 1H 00 1H01 1H02 1H03 1H04 1H05	1= average, 2= minimum, 3= maximum nput configuration (H11) Description Enable internal sensor Display minimum value Display maximum value Sensor sampling rate(control speed decrease as rate increases) Sensor calibration Alarm 3 low limit	Range           ON, OFF           -50205           -50205           0100           -10.010.0           OFF, ON	OFF 0 100 10 0 OFF
<b>nternal il</b> Parameter 1H 00 1H01 1H02 1H03 1H04 1H05 1H06	1= average, 2= minimum, 3= maximum nput configuration (HI1) Description Enable internal sensor Display minimum value Display maximum value Sensor sampling rate(control speed decrease as rate increases) Sensor calibration Alarm 3 low limit Alarm 1/3 low limit values	Range           ON, OFF           -50205           -50205           0100           -10.010.0           OFF, ON           0100%	OFF 0 100 10 0 0 0 FF 5%
<b>nternal il</b> Parameter 1H 00 1H01 1H02 1H03 1H04 1H05 1H06 1H07	1= average, 2= minimum, 3= maximum put configuration (H11) Description Enable internal sensor Display minimum value Display maximum value Sensor sampling rate(control speed decrease as rate increases) Sensor calibration Alarm 31 low limit Alarm 14 low limit values Alarm 4high limit	Range           ON, OFF           -50205           -50205           0100           -1010.0           OFF, ON           0100%           OFF, ON	OFF 0 100 10 0 0 0 FF 5% 0 FF

#### External input configuration (UI1, TI2)

Parar	neter	Description	Range	Standard
1u 00	2t 00	Signal type (0= not active): 1 = 010 V or 020mA or open contact, 2= 210V or 420mA, 3= NTC temperature sensor	03	0
1u 01	2t 01	Display minimum value	-50205	0
1u 02	2t 02	Display maximum value	-50205	100
1u 03	2t 03	Analog input display range: 0 = x0.1, 1 = x1, 2 = x10, 3 = x100	02	1
1u 04	2t 04	Analog input unit of measure: 0= no unit, 1= %, 2= °C /°F, 3= Pa	03	2
1u 05	2t 05	Sensor sampling rate (control speed decrease as rate increases)	0100	10
1u 06	2t 06	Sensor calibration	Range dep.	0
1u 07	2t 07	Alarm 5 low limit (1u), Alarm 7 low limit (2t)	OFF, ON	OFF
1u 08	2t 08	Alarm 5 low limit value (1u), Alarm 7 low limit value (2t)	-50205 °C	5°C (41°F)
1u 09	2t 09	Alarm 6 high limit (1u), Alarm 8 high limit (2t)	OFF, ON	OFF
1u 10	2t 10	Alarm 6 high limit value 1u), Alarm 8 high limit value (2t)	-50205 °C	50°C (122°F)
1u 11	2t 11	Hysteresis alarm 5 and 6 (1u), alarms 7 and 8 (2t)	0100 °C	5°C (10°F)
1u 12	2t 12	Calculate a range of inputs (0=not active): 1= average, 2= minimum, 3= maximum, 4= differential	04	0

# VECTOR

# Universal controller TCI-W13/23-W50



### Universal controller TCI-W13/23-W50

arameter	Description	Range	Standard
1L 00	Select loop control input (0= loop disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2T	04	1
1L 01	Minimum set point limit heating	per input	10°C(50°F
1L 02	Maximum set point limit heating	per input	28°C(82°F
1L 03	Minimum set point limit cooling	per input	18°C(64°F
1L 04	Maximum set point limit cooling	per input	34°C(93°F
1L 05	Enable set point compensation (0= disabled) 1= winter compensation, 2= summer compensation, 3= winter and summer	03	0
1L 06	Loop input special (0= normal): 1= combine loop 1 and loop 2 2= cascade with reverse sequence of primary loop 3= cascade with direct sequence primary loop 4= cascade with both reverse and direct sequence of primary loop	04	0
1L 07	Economy mode set point shift: (Function depends on 1L25) The comfort (occupied) set point is shifted by the value set with parameter. Reduces the heating set point and increases the cooling set point.	per input	5.0°C(10°F
1L 08	Dead zone between heating and cooling set points The dead zone span lies between the heating and the cooling set point. The output is off while the measured value is within the dead zone span. A negative dead zone is not possible.	Per input	1.0°C(2°F)
1L 09	Offset for heating PI sequence	per input	0
1L 10	Offset for cooling PI sequence	per input	0
1L 11	P-band heating	per input	2.0°C(4.0°
1L 12	P-band cooling	per input	2.0°(4.0°F
1L 13	Integral gain heating (0.1 steps) low= slow reaction, high= fast reaction	025.5	0.0
1L 14	Integral gain cooling (0.1 steps)	025.5	0.0
1L 15	Measuring interval integral (seconds) low= fast reaction, high value= slow reaction	0255	1
1L 16	Action of stages: 0=cumulative: stage 1 stays on when 2 on comes on 1=single: stage 1 turns off when 2 on comes on 2=digital: stage 1 only, stage 2 only, then stage 1 plus 2	02	0
1L 17	Offset for heating/reverse binary sequences	per input	0.0°C (0.0°l
1L 18	Offset for cooling/direct binary sequences	per input	0.0°C (0.0°
1L 19	Switching span heating	per input	1.0°C (2.0°
1L 20	Switching span cooling	per input	1.0°C (2.0°
1L 21	Switching hysteresis	per input	0.5°C (1.0°
1L 22		0255s	10s
1L 22	Switching delay Activation of reverse/direct (heat/cool) sequence	02005	105
1L 23	OFF=activates based on demand ON =follows heat/cool state of controller	ON/OFF	OFF
1L 24	Delay for heat /cool changeover when L23=OFF	0255 min	5 min
1L 25	Fixed set point in standby mode OFF = Standby set point shift applies ON = In standby mode use minimum set point limit as set point in backs a standby mode use minimum set point limit as set point in	ON, OFF	OFF
1L 26	heating mode or maximum set point limit in cooling mode Set point compensation range, the maximum range the set point is shifted. 0 = Temperature setback: the set point is shifted towards set point limit	Acc input	0.0°C

arameter	Description	Range	Standard
1A 00	Select control loop or special function (0= OFF): 1 = LP1, 2 = LP2 3 = Dehumidify (4 pipe, max LP1 cooling, LP2 direct) 4 = Manual positioning or time schedule controlled (0100%) 5 = Transmit value of an input	05	1
1A 01	When 1A00=1 configure output: 0= Heating/reverse 1= Cooling/direct 2= Heating and cooling (2 pipe) 3= Transmit set point When 1A00 = 4 manual positioning or time schedule controlled	04	2
	0 = time schedule controlled only 1 = manual positioning and time schedule controlled When 1A00=5, select input (0= function disabled):		
1A 02	1= 1T, 2= 1H, 3= 1U, 4= 2T Type of output signal: OFF= 010V, 020mA, ON= 210V, 420mA	ON, OFF	OFF (010V, 020mA)
1A 03	Minimum limitation of output signal default and in loop heating mode	0100 %	0
1A 04	Maximum limitation of output signal default and in loop heating mode	0100 %	100%
1A 05	Minimum limitation of output signal in loop cooling mode	0100%	0%
1A 06	Maximum limitation of output signal in loop cooling mode	0100%	100%
1A 07	Choose alarm to set output to 100% (output 0% on conflicting alarms) ママママママママ Alarm: 1 2 3 4 5 6 7 8	Selection	
1A 08	Choose alarm to set output to 0%. (output 0% on conflicting alarms) ママママママママ	Selection	
11.00	Alarm: 1 2 3 4 5 6 7 8	A	
1A 09	Transmit value (1A00=5): minimum input value	Acc input	-
1A 10	Transmit value (1A00=5): maximum input value	Acc input	-
arameter		Range	Standard
2A 00	Select control loop or special function (0= OFF): 1 = LP1, 2 = LP2 3 = Dehumidify (4 pipe, max LP1 cooling, LP2 direct) 4 = Manual positioning or time schedule controlled(0100%) 5 = Transmit value of an input	05	1
2A 01	When 1A00=1 configure output: 0= Heating/reverse 1= Cooling/direct 2= Heating and cooling (2 pipe) 3= Transmit set point When 1A00 = 4 manual positioning or time schedule controlled 0 = Time schedule controlled only 1 = Manual positioning and time schedule controlled When 1A00=5, select input (0= function disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2T	04	0
2A 02	Type of output signal: OFF= 010V, 020mA, ON= 210V, 420mA	ON, OFF	OFF (010V, 020mA)
2A 03	Minimum limitation of output signal default and in loop heating mode	0100 %	0
2A 04	Maximum limitation of output signal default and in loop heating mode	0100 %	100%
2A 05	Minimum limitation of output signal in loop cooling mode	0100%	0%
		0100 %	100%
2A 06	Maximum limitation of output signal in loop cooling mode		
2A 06 2A 07	Maximum limitation of output signal in loop cooling mode Choose alarm to set output to 100% (output 0% on conflicting alarms) ♡♡♡♡♡♡♡♡♡♡♡♡♡♡	Selection	
	Maximum limitation of output signal in loop cooling mode         Choose alarm to set output to 100%         (output 0% on conflicting alarms)         ♡♡♡♡♡♡♡♡         Alarm: 1 2 3 4 5 6 7 8         Choose alarm to set output to 0%.         (output 0% on conflicting alarms)         ♡♡♡♡♡♡		
2A 07	Maximum limitation of output signal in loop cooling mode Choose alarm to set output to 100% (output 0% on conflicting alarms) $\nabla \nabla \nabla \nabla \nabla \nabla \nabla \nabla \nabla \nabla$ Alarm: 1 2 3 4 5 6 7 8 Choose alarm to set output to 0%. (output 0% on conflicting alarms)	Selection	

2A 10 Transmit value (1A00=5): maximum input value

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Acc input

# VECTOR

Universal controller TCI-W13/23-W50

# Binary output – binary control

Parameter	Description	Range	Standard
	Enable digital or PWM output	ON, OFF	OFF
1d 00	OFF= 1d is a digital output	- , -	-
	ON = 1d is a PWM output		
1d 01	Select control loop or special function (0= OFF)	05	0
	1= LP1		
	2= LP2		
	3= Dehumidify (4 pipe, max LP1 cooling, LP2 direct)		
	4= Manual positioning (on/off)		
	5= State functions		
1d 02	When 1d01=1, configure output:	05	0
	0= Stage 1 heating/reverse		
	1= Stage 1 cooling/direct		
	2= Stage 1 heating and cooling, reverse and direct		
	3= Stage 2 heating/reverse		
	4= Stage 2 cooling/direct		
	5= Stage 2 heating and cooling, reverse and direct		
	If 1d01 = 4 manual positioning or time schedule controlled		
	0 = Time schedule controlled only		
	1 = Manual positioning and time schedule controlled		
	When 1d01=5, select state functions:		
	0= ON if controller operation state is ON		
	1= ON while demand on any output		
	2= ON while controller in heating mode and operation		
	state ON		
	3= ON while controller in cooling mode and operation state ON		
1d 03	Switch-off delay (time output active with no more demand)	0255s	90s
	Delay is in seconds or minutes depending on d09		
1d 04	Switch-on delay (time demand active before output on).	0255s	5s
	In state mode 1d01=5 outputs disabled during switch-on delay.		
	Delay is in seconds or minutes depending on d09.		
1d 05	Activate PWM, set cycle time, seconds (>0 activates, 0 deactivates)	01275	0
1d 06	Choose alarm to set output to ON (output OFF on conflicting alarms)	Selection	$\Delta\Delta\Delta\Delta\Delta\Delta\Delta\Delta\Delta$
	$\Delta\Delta\Delta\Delta\Delta\Delta\Delta\Delta\Delta$		
	Alarm: 1 2 3 4 5 6 7 8		
1d 07	Choose alarm to set output to OFF	Selection	$\nabla \Delta \Delta \Delta \Delta \Delta \Delta \Delta \Delta$
	(output OFF on conflicting alarms)		
	Alarm: 1 2 3 4 5 6 7 8		
1d 08	Display fan symbol while active	ON, OFF	OFF
1d 09	Binary switching delays in minutes or seconds	ON, OFF	OFF
10.03	OFF = delays are in seconds, ON = delays are in minutes	011,011	0.1

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v	ECT	<b>OR</b>	
		VIX	

# Universal controller TCI-W13/23-W50 VE



### Special functions – SP compensation

	Description	Range	Standard
Fu 00	Select compensation input (0= function disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2T	04	0
Fu 01	Winter compensation set point setback OFF= shift toward control loop heating set point minimum ON= shift toward control loop heating set point maximum	ON, OFF	OFF
Fu 02	Winter compensation lower limit value – end shift	Range acc input	5°C
Fu 03	Winter compensation upper limit value – start shift	Range acc input	20°C
Fu 04	Summer compensation set point setback OFF= shift toward control loop cooling set point minimum ON= shift toward control loop cooling set point maximum	ON, OFF	ON
Fu 05	Summer compensation lower limit value – start shift	Range acc input	35°C
Fu 06	Summer compensation upper limit value – end shift	Range acc input	40°C
Fu 07	Show hot/cool symbol while compensation active	ON, OFF	OFF
Special fu	unctions – remote control comfort – economy		
Fu 08	Select comfort/economy changeover input (0= disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2T	04	0
Fu 09	Economy activation delay (seconds)	01275	300
Fu 10	Input limit 1	Range acc input	10
Fu 11	Input limit 2	Range acc input	90
Fu 12	Select enable-disable input (0=function disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2T	04	0
Fu 12 FU 13		04 ON, OFF	0 OFF
	1= 1T, 2= 1H, 3= 1U, 4= 2T Manual override permitted (without waiting for delay). This function allows starting the controller; although the enable conditions are not met. The controller will switch off again if the	-	•
FU 13	1= 1T, 2= 1H, 3= 1U, 4= 2T Manual override permitted (without waiting for delay). This function allows starting the controller, although the enable conditions are not met. The controller will switch off again if the running conditions are not met until the disable delay is expired. Enable delay (seconds)	ON, OFF 01275	OFF 0
FU 13	1= 1T, 2= 1H, 3= 1U, 4= 2T Manual override permitted (without waiting for delay). This function allows starting the controller; although the enable conditions are not met. The controller will switch off again if the running conditions are not met until the disable delay is expired.	ON, OFF	OFF
FU 13 Fu 14 Fu 15	1= 1T, 2= 1H, 3= 1U, 4= 2T Manual override permitted (without waiting for delay). This function allows starting the controller, although the enable conditions are not met. The controller will switch off again if the running conditions are not met until the disable delay is expired. Enable delay (seconds) Disable delay (seconds)	ON, OFF 01275 01275	0 0 300
FU 13 Fu 14 Fu 15	1= 1T, 2= 1H, 3= 1U, 4= 2T Manual override permitted (without waiting for delay). This function allows starting the controller, although the enable conditions are not met. The controller will switch off again if the running conditions are not met until the disable delay is expired. Enable delay (seconds) Disable delay (seconds) Range of limits: OFF = When limit 2 is greater than limit 1, enable when input value is greater than limit 2,disable when input value less than limit 1, disable when input value	ON, OFF 01275 01275	0 0 300
FU 13 Fu 14 Fu 15	1= 1T, 2= 1H, 3= 1U, 4= 2T         Manual override permitted (without waiting for delay).         This function allows starting the controller, although the enable conditions are not met. The controller, although the enable conditions are not met until the disable delay is expired.         Enable delay (seconds)         Disable delay (seconds)         OFF =       When limit 2 is greater than limit 1, enable when input value is greater than limit 2, disable when input value is less than limit 1.         When limit 2 is less than limit 1, enable when input value less than limit 2.         ON =       When limit 2 is greater than limit 1, enable when input value is between limit 1, enable when input value is greater than limit 1, enable when input value is greater than limit 1, enable when input value less than limit 1.	ON, OFF 01275 01275	0 0 300
FU 13 Fu 14 Fu 15 Fu 16	1= 1T, 2= 1H, 3= 1U, 4= 2T         Manual override permitted (without waiting for delay).         This function allows starting the controller, although the enable conditions are not met. The controller, although the enable starting conditions are not met until the disable delay is expired.         Enable delay (seconds)         Disable delay (seconds)         Range of limits:         OFF =       When limit 2 is greater than limit 1, enable when input value is greater than limit 1, disable when input value is greater than limit 1, enable when input value [ses than limit 1, disable when input value [ses than limit 1.         ON =       When limit 2 is greater than limit 1, enable when input value is greater than limit 1.         When limit 2 is less than limit 1, enable when input value between limit 1.         When limit 2 is greater than limit 1, enable when input value less than limit 2.         ON =       When limit 2 is greater than limit 1, enable when input value between limit 1 and limit 2.	ON, OFF 01275 01275 ON, OFF	0 0 300 0FF

# Special functions – remote heat / cool (reverse / direct) change

Fu 20	Select heat/cool changeover input (0=function disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2T,	06	0
Fu 21	5= h/c status loop 1, 6= h/c status loop 2 Cooling activation delay (seconds)	01275	300
Fu 22	Input limit 1	Range acc input	20
Fu 23	Input limit 2	Range acc input	40