TCI-W Universal controller

General description

The TCI-W is a stand-alone wall mounted electronic universal controller with two autonomous control loops. Each control loop may use up to 2 PID sequences and 6 binary sequences. The TCI-W11 features independent control loop, 1 universal input, 2 binary outputs and 1 analog output, the TCI-W22 offers 2independent control loops, 2 universal inputs, 2 binary relays outputs and 1 analog output. A detailed configuration is possible by following a simple setup routine. The TCI can be configured using the standard operation terminal. No special tool or software is required.

Ordering, name convention

CI-W22-U	Optional functions and hous	sing
	Housing	U = 2 x 4" type housing, Blank = square housing
	In-/Outputs:	1 = 1UI, 2DOR, 1AO, 2 = 2UI, 2DOR, 1AO
	Control loops:	1 = 1 control loop, 2 = 2 control loops
L	Mounting:	W = Wall mounted
Ĺ	Series indication	TCI

Item name	Item code	Loop	Int. temperature		Universal input	Binary output	Analog output	Option
TCI-W11	40-10 0073	1	1	0	1	2	1	Standard
TCI-W11-H	40-10 0162	1	1	1	1	2	1	RH Sensor 3%
TCI-W22	40-10 0075	2	1	0	2	2	1	Schedules
TCI-W22-H	40-10 0077	2	1	1	2	2	1	RH Sensor 3%

7,0000007100	Accessories							
AES1-HT-A2	40-50 0067			1				RH Sensor 2%
AES1-HT-A3	40-50 0068			1				RH Sensor 3%
AES1-HT-A5	40-50 0069			1				RH Sensor 5%

Selection of actuators and sensors

Temperature sensors: Use only our approved NTC sensors to achieve maximum accuracy. Recommended is SDB-Tn10 as duct sensor. SRA-Tn10 as room sensor.

Modulating actuators: Choose actuators with an input signal type of 0...10 VDC or 4...20 mA. Minimum and maximum signal limitations may be set in software.

Binary auxiliary devices: E.g. pumps, fans, on/off valves, humidifiers, etc. Do not directly connect devices that exceed the maximum limits as described under technical data. Observe startup current on inductive loads

Jumper configuration

Accessories

Jumpers are mounted vertically only.

- . AO Selection of output signal type:
 - Left position: voltage output (0...10 V), factory default
 - Right position: current output (0...20 mA)
- AI Selection of input signal type:
 - Left position: voltage input (0...10 V), factory default
 - o Middle position: current input (0...20 mA)
 - o Right position: RT or dry-contact input

Α	0		UΙ	
010 V	020 mA	010 V	020 mA	RT or contact
•		ı		

Mounting location

- Install the controller on an easy accessible interior wall, approx. 1.5 m above the floor in an area of average temperature.
- Avoid direct sunlight or other heat sources, e.g. the area above radiators and heat emitting equipment.
 Avoid locations behind doors, outside walls and below or above air discharge grills and diffusers.
- Location of mounting is less critical if external temperature sensors are used.

Installation

- 1. Connect the wires to be connected to the terminals of the power case according to wiring diagram
- Install the mounting plate to the flush mounting box. Make sure that the nipple with the front holding screw is facing to the ground. Make sure the mounting screw heads do not stand out more than 5 mm (0.2") off the surface of the mounting plate.
- 3. Ensure that the jumpers are set correctly.
- Slide the two latches located on the top of the front part into the hooks at the upper side of the
 mounting plate.
- Carefully lower the front part until the interconnector reaches the mounting-plate. Continue pressing in a gentle way until the front part is fully connected. While inserting the connectors, a slight resistance can be felt. This is normal. Do not use excessive force!
- With a Philips-type screw driver of size #2, carefully tighten the front holding screw to secure the front part to the mounting plate. This screw is located on the front lower side of the unit. There is no need to tighten the screw too much.

Technical specification

Warning! This device is intended to be used for comfort applications. Where a device failure endangers human life and/or property, it is the responsibility of the owner, designer and installer to add additional safety devices to prevent or detect a system failure caused by such a device failure. The manufacturer of this device cannot be held liable for any damage caused by such a failure.

Failure to follow specifications and local regulations may endanger life, cause equipment damage and void warranty.

Power supply	Operating voltage	ger life, cause equipment damage and void warranty. 24 VAC 50/60 Hz ± 10%
	Power consumption	Max 3 VA
	Electrical connection	Terminal connectors,
		wire 0.342.5 mm ² (AWG 2213)
	Clock backup	24 hours (deluxe version only)
Signal inputs	Analog inputs	UI1, UI2
	Input signal Resolution	DC 010 V or 020 mA 39 mV or 0.078 mA
	Impedance	Voltage: 98kΩ Current: 240Ω
	Temperature Inputs	RT Internal, External (Sxx-Tn10 sensor)
	Range	Int. NTC: 050 °C (32122 °F)
	95	Ext. NTC: -40140 °C (-40284 °F)
	Resolution	0.1 K
	Accuracy	-400 °C (-4032 °F): 0.5 K
		050 °C (32122 °F): 0.2 K
		50100 °C (122212 °F): 0.5 K > 100 °C (> 212 °F): 1 K
	11 15 AFO UT A	
	Humidity sensor AES-HT-Ax: Range	Capacity sensor 0100% RH
	Measuring accuracy	See Figure below
	Hysteresis	± 1%
	Repeatability	± 0.1%
	Stability	< 0.5% / year
Signal outputs	Analog outputs	AO1
• .	Output signal	DC 010 V or 020 mA
	Resolution	39 mV, 0.078 mA
	Maximum load	Voltage: ≥1 kΩ Current: ≤250Ω
	Relays outputs	
	Type of disconnection	Micro-interruption
	AC voltage	0250 VAC, 2(1.2)A max. Observe local regulations 030 VDC, 2A max.
	DC voltage	U30 VDC, 2A max.
	Insulation strength	
	between relays contacts and system	
	electronics: between neighboring contacts:	2000 VAC to EN 60730-1 1250 VAC to EN 60730-1
Environment	Operation	To IEC 721-3-3
Liviloilileit	Climatic conditions	class 3K5
	Temperature	050 °C (32122 °F)
	Humidity	<95 % RH non-condensing
	Transport &storage	To IEC 721-3-2 and IEC 721-3-1
	Climatic conditions	class 3K3 and class 1K3
	Temperature	-2570 °C (-13158 °F)
	Humidity Mechanical conditions	< 95% RH non-condensing class 2M2
Standards	conform according to	CidSS ZIVIZ
Staridards	EMC Standard	
	EMEI Standard 73/23/EEC	EN 61000-6-1/ EN 61000-6-3
	Product standards	
	Automatic electrical controls for	EN 60730-1
	household and similar use	=11.00=0.0
	Special requirement on temperature dependent controls	EN 60730-2-9
		IP30 to EN 60529
	Degree of protection	
	Pollution class	II (EN 60 730-1) II (IEC 60536) if voltage on DO > 48V
	Safety class	III (IEC 60536) if voltage on DO > 48V III (IEC 60536) if voltage on DO < 48V
	Overvoltage category	I (EN 60730-1)
Housing	Materials: Cover, back part	Fire proof ABS plastic (UL94 class V-0)
	Mounting plate	Galvanized steel
General	Dimensions (H x W x D)	Front part: 88 x 88 x 21 mm (3.5" x 3.5" x 0.8")
	1	Power case: ø 58 x 32 mm (ø 2.3" x 1.3")
	Weight (including package)	TCI-W11 = 250g (8.8 oz) TCI-W22 = 265g (9.3oz)

Power failure

Upon power-interruption, all parameters and set points are memorized in non-volatile memory, and therefore do not have to be re-entered.

Error messages

An assigned input is not enabled or missing. All control loops, functions and outputs tied to this input will be disabled Verify input connections, jumper settings and parameter settings for the input involved.

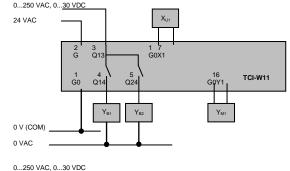
Err3: A function refers to a disabled input.
Disable the function or enable the input.
Err4: Internal failure. Product must be replaced.

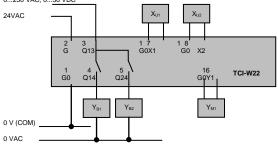
%RH Relative humidityaccuracy 45 44 43 43 48S-HT-A3 42 40 0 10 20 30 40 50 60 70 80 90 100 Figure 1: Max RH-tolerance at 25°C (77°F) per sensor type

Wiring diagram

Warning: Live electrical components

During installation, testing, servicing and troubleshooting of Vector Controls products, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

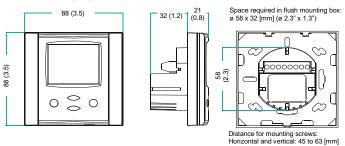




Description

G0 Power supply: 0 V, -24VDC; common for power supply, analog in- and outputs 24VAC, +24VDC Power supply a Potential free relays output (see technical specification) Binary outputs: NTC 10kΩ @ 25 °C (77 °F), 0...10 V or 0...20 mA X_{U..} Universal input: 0...10 V or 0...20 mA Analog output: Internal temperature input Internal humidity input: only for TCI-W22-H models

Dimensions mm (inch)



Controller configuration

Proceed in the following steps in order to adapt the controller to its application:

- Set jumpers for inputs and outputs
- Connect power supply and inputs
- Program input parameters
- Program control parameters Program output parameters
- Test function of unit
- Switch off power
- Connect outputs
- Test control loop
- Set user settings

Configuration parameters for firmware version 1.1

The TCI-W can be adapted to wide variety of applications. The adaptation is done with parameters. The parameters can be changed on the unit without the need of additional equipment.

Identifying the firmware version

The parameters and functionality of controller depend on its firmware revision. It is therefore important to use a matching product version and parameter set. The firmware version is marked on the package box of your product. In order to identify the firmware version of an installed controller, press UP and DOWN keys simultaneously for three seconds: The display will indicate the firmware version in the upper large digits and the revision in the lower small digits. Press the LEFT key to return to normal operation.

Changing the parameters

- Press UP and DOWN button simultaneously for three seconds. The display will indicate the firmware version in the upper large digits and the revision in the lower small digits. Press the RIGHT or POWER key to start login
- CODE is shown in small display.
- The code for accessing the user parameters is 0009, for control parameters it is 0241 3.
- 4. Select this using UP or DOWN buttons.
- Press the RIGHT or POWER button after selecting the correct code. 5.
- Once logged in the parameter group can be selected with the UP and DOWN key. Enter the 6. group with the RIGHT or POWER key.
- 7. Once the group is selected, the parameter is displayed immediately
- Select the parameters with the UP/DOWN buttons. Change a parameter by pressing the RIGHT button. Arrows 8 to 10 show up and indicate that the parameter may be modified now. Use UP or DOWN buttons to adjust the value.
- After you are done, press RIGHT or POWER in order to save the new value of the parameter and return to the selection level. Pressing LEFT key will discard the value and return to the selection menu without saving.
- Press the LEFT key again so as to leave the parameter menu and return to the group selection. Press LEFT key again while in the group selection to return to normal operation.
- The unit will return to normal operation if no key is pressed for more than 5 minutes.

User parameters (password 09)

Parameter	Description				Range	Default
UP 00	Enable access t	o operation mo	des		ON, OFF	ON
UP 01	Enable access	to set points			ON, OFF	ON
UP 02	Enable manual	control in casca	ide or fan control i	node	ON, OFF	ON
UP 03	Enable change	of heating/cooling	ng mode for 2 pip	e systems	ON, OFF	ON
UP 04	Enable access to	time program	S:		ON, OFF	ON
UP 05	State after power	r failure:			0, 1, 2	2
	0 = off, 1 = on,	2 = state before				
UP 06	Enable Economy (unoccupied) Mode.				ON, OFF	ON
			nperature in winte			
			r to save energy.			
			OWER button, or ches in hotel roor			
	detectors for me		cries in notei roor	ns or motion		
LID 07	UP 07 Celsius or Fahrenheit: ON = Fahrenheit, OFF = Celsius					OFF (Celsiu
UP 08	Show standard			Celsius	ON, OFF	ON ON
UP 09			display in standard	mode.	05	1
01 00	00 = OFF	or Large LOD o	03 = Analog Ou		00	
	01 = Input		04 = Binary Ou			
	02 = Set point		05 = Clock			
UP 10	Select ID of con	tents of upper o	ligit display		04	1
	Input:	Set point:	Analog or	Binary output:		
	1 = 1T	1 = Lp1	floating output:			
	2 =1H	2 =Lp2	1 = AO1	2 - DO2		
	3 = 1U		2 = FO1			
	4 = 2U			L		
UP 11	Select contents	of lower digit di	splay in standard	mode	05	TCI-W11 = : TCI-W22 =
UP 12	Select ID of con	tents of lower d	ligit display		04	1
UP 13	Select analog or	tput for display	in vertical bar		04	3
	00 = OFF					
	01 = AO1					
	02 = FO1					
	03 = Output lp1 04 = Output lp2					
UP 14		cooling state in	standard display	mode	ON, OFF	OFF
UP 15			active and need to		ON, OFF	ON
	OFF = Alarms a	re only shown		-		
UP 16 (TCI-W22)	Clock display typ	oe: OFF = 24-	ON, OFF	OFF		
UP 17		nanual override	of time schedule	:	0255	60
(TCI-W22)						
			ase the controller			
				The controller will		
	return to schedu	led function aft	er expiration of th	s delay.		

Control parameters (password 241)

Warning! Only experts should change these settings! The parameters are grouped according to control modules. After completing the logging in, a control module must be selected before accessing the parameters.

-	·
Module	Description
UI	Input configuration: 1T, 1H, 1U, 2U
LP	Control loops Lp1, Lp2
AO	Analog output configuration, AO1
DO	Binary output configuration, DO1, DO2
FU	Special functions

Internal input configuration (TI1)

Parameter	Description	Range	Standard
1t 00	Enable internal sensor	ON, OFF	ON
1t 01	Display minimum value	-50205	0
1t 02	Display maximum value	-50205	100
1t 03	Sensor sampling rate(control speed decrease as rate increases)	0100	10
1t 04	Sensor calibration	-10.010.0	0
1t 05	Alarm 1 low limit (1T), Alarm 3 low limit (1H)	OFF, ON	OFF
1t 06	Alarm 1/3 low limit values	-50205 °C	5 °C (41 °F)
1t 07	Alarm 2high limit (1T), Alarm 4high limit (1H)	OFF, ON	OFF
1t 08	Alarm 2/4 high limit values	-50205 °C	50 °C (122 °F)
1t 09	Hysteresis Alarm 1, 2, 3, 4	0100 °C	5 °C (10 °F)
1t 10	Calculate a range of inputs (0 = not active): 1 = average, 2 = minimum, 3 = maximum	03	0

Internal input configuration (HI1)

Parameter	Description	Range	Standard
1H 00	Enable internal sensor	ON, OFF	OFF
1H01	Display minimum value	-50205	0
1H02	Display maximum value	-50205	100
1H03	Sensor sampling rate(control speed decrease as rate increases)	0100	10
1H04	Sensor calibration	-10.010.0	0
1H05	Alarm 1 low limit (1T), Alarm 3 low limit (1H)	OFF, ON	OFF
1H06	Alarm 1/3 low limit values	0100%	5%
1H07	Alarm 2high limit (1T), Alarm 4high limit (1H)	OFF, ON	OFF
1H08	Alarm 2/4 high limit values	0100%	95%
1H09	Hysteresis Alarm 1, 2, 3, 4	0100%	5%
1H10	Calculate a range of inputs (0 = not active): 1 = average, 2 = minimum, 3 = maximum	03	0

Universal input configuration (UI1, UI2)

Parameter	Description	Range	Standard
1u 00	Signal type (0 = not active): 1 =010 V or 020 mA, 2 = 210 V or 420 mA, 3 = passive temperature	03	0
1u 01	Display minimum value	-50205	0
1u 02	Display maximum value	-50205	100
1u 03	Analog input display range: $0 = x0.1$, $1 = x1$, $2 = x10$, $3 = x100$	02	1
1u 04	Analog input unit of measure: $0 = \text{no unit}$, $1 = \%$, $2 = {^{\circ}\text{C}}/{^{\circ}\text{F}}$, $3 = \text{Pa}$	03	2
1u 05	Sensor sampling rate (control speed decrease as rate increases)	0100	10
1u 06	Sensor calibration	Range dep	0
1u 07	Alarm 5 low limit (1U)	OFF, ON	OFF
1u 08	Alarm 5 low limit value	-50205 °C	5 °C (41 °F)
1u 09	Alarm 6 high limit (1U)	OFF, ON	OFF
1u 10	Alarm 6 high limit value	-50205 °C	50 °C (122 °F)
1u 11	Hysteresis alarm 5 and 6	0100°	5 °C (10 °F)
1u 12	Calculate a range of inputs (0 =not active): 1 = average, 2 = minimum, 3 = maximum, 4 = differential	04	0

LP: Control parameters (1L to 2L)

Parameter	Description	Range	Standard
1L 00	Select loop control input (0 = loop disabled): 1 = 1T, 2 = 1H, 3 = 1U, 4 = 2U	04	1
1L 01	Minimum set point limit heating	per input	10 °C(50 °F)
1L 02	Maximum set point limit heating	per input	28 °C(82 °F)
1L 03	Minimum set point limit cooling	per input	18 °C(64 °F)
1L 04	Maximum set point limit cooling Enable set point compensation (0 = disabled)	per input	34 °C(93 °F)
1L 05	1 = winter compensation, 2 = summer compensation, 3 = winter and summer	03	0
1L 06	Loop input special (0 = normal): 1 = combine loop 1 and loop 2 2 = cascade with reverse sequence of primary loop 3 = cascade with direct sequence primary loop 4 = cascade with both reverse and direct sequence of primary loop	04	0
1L 07	Economy mode set point shift: (Function depends on 1L25) The comfort (occupied) set point is shifted by the value set with parameter. Reduces the heating set point and increases the cooling set point.	per input	5.0 °C(10 °F)
1L 08	Dead zone between heating and cooling set points The Dead Zone Span lies between the heating and the cooling set point. The output is off while the measured value is within the dead zone span. A negative dead zone is not possible.	Per input	1.0°(2 °F)
1L 09	Offset for heating PI sequence	per input	0
1L 10	Offset for cooling PI sequence	per input	0
1L 11	P-band heating	per input	2.0 °C (4.0 °F)
1L 12	P-band cooling	per input	2.0°C (4.0 °F)
1L 13	Integral gain heating (0.1 steps) Iow = slow reaction, high = fast reaction	025.5	0.0
1L 14	Integral gain cooling (0.1 steps)	025.5	0.0
1L 15	Measuring interval integral (seconds) low = fast reaction, high value = slow reaction	0255	1
1L 16	Action of stages: 0 =cumulative: stage 1 stays on when 2 on comes on 1 =single: stage 1 turns off when 2 on comes on 2 = digital: stage 1 only, stage 2 only, then stage 1 plus 2	02	0
1L 17	Offset for heating/reverse binary sequences	per input	0.0°C (0.0 °F)
1L 18	Offset for cooling/direct binary sequences	per input	0.0°C (0.0 °F)
1L 19	Switching span heating	per input	1.0°C (2.0 °F)
1L 20	Switching span cooling	per input	1.0°C (2.0 °F)
1L 21	Switching hysteresis	per input	0.5°C (1.0 °F)
1L 22	Switching delay	0255s	10s
1L 23	Activation of reverse/direct (heat/cool) sequence OFF = activates based on demand ON =follows heat/cool state of controller	ON/OFF	OFF
1L 24	Delay for heat /cool changeover when L23 =OFF	0255 min	5 min
1L 25	Fixed set point in standby mode OFF = Standby set point shift applies ON = In standby mode use minimum set point limit as set point in heating mode or maximum set point limit in cooling mode	ON, OFF	OFF
1L 26	Set point compensation range, the maximum range the set point is shifted. 0 = Temperature setback: the set point is shifted towards set point limit	Acc input	0.0 °C

Analog output

Parameter		Range	Standard
1A 00	Select control loop or special function (0 = OFF): 1 = LP1, 2 = LP2	05	1
	2 = LP2 3 = Dehumidify (4 pipe, max LP1 cooling, LP2 direct) 4 = Manual positioning or time schedule controlled(0100%)		
	5 =Transmit value ofan input		
1A 01	When 1A00 =1 configure output: 0 = Heating/reverse 1 = Cooling/direct 2 = Heating and cooling (2 pipe) 3 = Transmit set point	04	0
	When 1A00 = 4 Manual positioning or time schedule controlled 0 = time schedule controlled only 1 = manual positioning and time schedule controlled		
	When 1A00 =5, select input (0 =function disabled): 1 = 1T, 2 = 1H, 3 =1U, 4 =2U		
1A 02	Type of output signal: OFF =010 V, 020 mA, ON =210 V, 420 mA	ON, OFF	OFF (010 V, 020 mA)
1A 03	Minimum limitation of output signal default and in loop heating mode	0100%	0
1A 04	Maximum limitation of output signal default and in loop heating mode	0100%	100%
1A 05	Minimum limitation of output signal in loop cooling mode	0100%	0%
1A 06	Maximum limitation of output signal in loop cooling mode	0100%	100%
1A 07	Choose alarm to set output to 100% (output 0% on conflicting alarms) □□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□	Selection	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\
1A 08	Choose alarm to set output to 0%. (output 0% on conflicting alarms) マンマンマンマ Alarm: 1 2 3 4 5 6 7 8	Selection	
1A 09	Transmit value (1A00 =5): minimum input value	Acc input	-
1A 10	Transmit value (1A00 =5); maximum input value	Acc input	-

Binary output - 3-point control

Parameter	Description	Range	Standard
1d 00	Enable digital orfloating point output OFF =1d and 2D are two digital outputs ON =1d and 2D are one floating point output (1d open,2D close)	ON, OFF	OFF
1d 01	Select control loop or special function (0 = OFF) 1 = LP1, 2 = LP2 3 = Dehumidify (4 pipe, max LP1 cooling, LP2 direct) 4 = Manual positioning (open/dlose) 5 = Controller state functions	05	0
1d 02	If 1001 =1 configure output: 0 = Heating/revrse 1 = Cooling/direct 2 = Heating and cooling (2 pipe) If 1001 = 4 Manual positioning or time schedule controlled 0 = time schedule controlled only 1 = manual positioning and time schedule controlled If 1001 =5 select state functions:	05	0
	0 = ON if controller operation state is ON 1 = ON while demand on any output 2 = ON while controller in heating mode and operation state ON 3 = ON while controller in cooling mode and operation state ON		
1d 03	Running time (from open to close)	0255s	90s
1d 04	Switching difference for floating point signal	0100s	5s
1d 05	Not used	01275 s	0s
1d 06	Choose alarm to set output to 100% (output 0% on conflicting alarms) ママッマッマッマ Alarm: 1 2 3 4 5 6 7 8	Selection	
1d 07	Choose alarm to set output to 0% (output 0% on conflicting alarms) マママママママ Alarm: 1 2 3 4 5 6 7 8	Selection	$\nabla\nabla\nabla\nabla\nabla\nabla\nabla$
1d 08	Not used	ON, OFF	OFF
1d 09	Not used	ON, OFF	OFF

Binary output - binary control

Parameter		Range	Standard
1d 00	Enable digital orfloating point output	ON, OFF	OFF
	OFF =1d and 2D are two digital outputs		
	ON = 1d and 2D are one floating point output		
	(1d open,2D close)		
1d 01	Select control loop or special function (0 = OFF)	05	0
	1 = LP1 2 = LP2		
	3 = Dehumidify (4 pipe, max LP1 cooling, LP2 direct) 4 = Manual positioning (on/off)		
	5 = State functions		
	When 1d01 =1, configure output:		_
1d 02	0 = Stage 1 heating/reverse	05	0
	1 = Stage 1 reating/reverse 1 = Stage 1 cooling/direct		
	2 = Stage 1 cooling and cooling, reverse and direct		
	3 = Stage 2 heating/reverse		
	4 = Stage 2 cooling/direct		
	5 = Stage 2 heating and cooling, reverse and direct		
	If 1d01 = 4 Manual positioning or time schedule controlled		
	0 = time schedule controlled only		
	1 = manual positioning and time schedule controlled		
	When 1d01 =5, select state functions:		
	0 = ON if controller operation state is ON		
	1 = ON while demand on any output		
	2 = ON while controller in heating mode and operation		
	state ON		
	3 = ON while controller in cooling mode and operation		
	state ON		
1d 03	Switch-off delay (time output active with no more demand)	0255	90
	Delay is in seconds or minutes depending on d09		
1d 04	Switch-on delay (time demand active before output on)	0255	5
	In state mode 1d01 =5 outputs disabled during switch-on delay		
	Delay is in seconds or minutes depending on d09		
1d 05	Activate PWM, set cycle time, seconds	01275	0
	(>0 activates, 0 deactivates)		
1d 06	Choose alarm to set output to ON (output OFF on conflicting	Selection	$\triangle\triangle\triangle\triangle\triangle\triangle\triangle\triangle$
	alarms)		
	$\nabla\nabla\nabla\nabla\nabla\nabla\nabla\nabla$		
	Alarm: 1 2 3 4 5 6 7 8		
1d 07	Choose alarm to set output to OFF (output OFF on conflicting	Selection	$\triangle \triangle \triangle \triangle \triangle \triangle \triangle \triangle \triangle$
	alarms)		
	$\nabla\nabla\nabla\nabla\nabla\nabla\nabla\nabla\nabla$		
	Alarm: 1 2 3 4 5 6 7 8		
1d 08	Display fan symbol while active	ON, OFF	OFF
1d 09	Binary switching delays in minutes or seconds	ON, OFF	OFF
10 05	OFF = delays are in seconds, ON = delays are in minutes	OIN, OI I	011
	Of 1 = delays are in seconds, ON = delays are in initiates		

Special functions - SP compensation

Parameter	Description	Range	Standard		
Fu 00	Select compensation input (0 = function disabled): 1 = 1T, 2 = 1H, 3 = 1U, 4 = 2U	04	0		
Fu 01	Winter compensation set point setback OFF = shift toward control loop heating set point minimum ON = shift toward control loop heating set point maximum	ON, OFF	OFF		
Fu 02	Winter compensation lower limit value - end shift	Range acc input	5 °C		
Fu 03	Winter compensation upper limit value - start shift	Range acc input	20 °C		
Fu 04	Summer compensate onset point setback OFF = shift toward control loop cooling set point minimum ON = shift toward control loop cooling set point maximum	ON, OFF	ON		
Fu 05	Summer compensation lower limit value - start shift	Range acc input	35 °C		
Fu 06	Summer compensation upper limit value - end shift	Range acc input	40 °C		
Fu 07	Show hot/cool symbol while compensation active	ON, OFF	OFF		
Special functions - remote control comfort - economy					

Special functions - remote control comfort - economy

Fu 08	Select comfort/economy changeover input (0 = disabled): 1 = 1T, 2 = 1H, 3 = 1U, 4 = 2U	04	0
Fu 09	Economy activation delay (seconds)	01275	300
Fu 10	Input limit 1	Range acc input	10
Fu 11	Input limit 2	Range acc input	90

Special functions - remote control enable - disab

Special functions - remote control enable - disable				
Fu 12	Select enable-disable input (0 =function disabled): 1 = 1T, 2 = 1H, 3 = 1U, 4 = 2U	04	0	
FU 13	Manual override permitted (without waiting for delay). This function allows starting the controller; although the enable conditions are not met. The controller will switch off again if the running conditions are not met until the disable delay is expired.	ON, OFF	OFF	
Fu 14	Enable delay (seconds)	01275	0	
Fu 15	Disable delay (seconds)	01275	300	
Fu 16	Range of limits: OFF = When limit 2 is greater thanlimit 1, enable when input value is greater than limit 2,disable when input value is less thanlimit 1. When limit 2 is less thanlimit 1, enable when input value less than limit 1, disable when input value is greater thanlimit 2. ON = When limit 2 is greater thanlimit 1 enable when input value is between limit 1 and limit 2. When limit 2 is less thanlimit 1, enable when input value below limit 2 or above limit 1.	ON, OFF	OFF	
Fu 17	Input limit 1	Range acc input	10	
Fu 18	Input limit 2	Range acc input	90	
Fu 19	Disable in case of alarms	Selection	$\triangle\triangle\triangle\triangle\triangle\triangle\triangle\triangle$	

Special functions - remote heat / cool (reverse / direct) change

Fu 20	Select heat/cool changeover input (0 =function disabled): 1 = 1T, 2 = 1H, 3 = 1U, 4 = 2U, 5 = h/c status loop 1, 6 = h/c status loop 2	06	0
Fu 21	Cooling activation delay (seconds)	01275	300
Fu 22	Input limit 1	Range acc input	20
Fu 23	Input limit 2	Range acc input	40