

TCI-C series cabinet mounted universal controller



Features

- Universal PID and/or binary control for any analog input/output signal and range
- Multiple auxiliary functions: heat-cool auto changeover, automatic enable, set point compensation
- Differential, averaging, min. and max. functions
- Cascading of control loops (-C22 type)
- Alarm monitoring of low and high limits on all inputs
- Programmable reaction in case of alarm
- Feedback function for inputs and set points
- Functions for dehumidifying, set point shift, cascade control
- Password protected programmable user and control parameters

TCI-C22 also includes

- Power cap protected real-time clock with 48 hr power backup
- 7-day programmable schedules, with options including change of set points and direct position of manual outputs
- Blue backlight

Applications

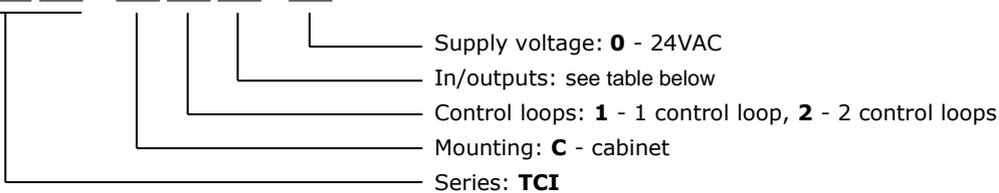
- Heat exchangers
- Zoning
- Boilers
- VAV
- Air handlers
- Fan, pump control
- Humidifiers
- Dehumidifiers
- Ventilation
- Radiant heating
- Radiant cooling
- Pressurization

General

- TCI-C11: 1 independent control loop, 2 universal inputs (analog/binary/temp), 2 binary outputs, 1 analog output
- TCI-C22: 2 independent control loops, 4 universal inputs, 2 binary outputs, 2 analog output2.
- Flexible application configuration is made with a parameter-setting routine using the standard operation terminal.

Name

T C I - C 2 2 - 0



Ordering

Model	Order code	Power	Option	Loop	Input	Temp	Binary output	Analog output
TCI-C11-0	40-11 0060	24 VAC	Standard	1	2	NTC	2 relays	1
TCI-C13-0	40-11 0064	24 VAC	Standard	1	2	NTC	2 TRIAC	1
TCI-C22-0	40-11 0062	24 VAC	Schedules	2	4	NTC	2 relays	2
TCI-C14-0	40-11 0071	24 VAC	Standard	1	2	PT/NI1000	2 relays	1
TCI-C15-0	40-11 0067	24 VAC	Standard	1	2	PT/NI1000	2 TRIAC	1
TCI-C24-0	40-11 0070	24 VAC	Schedules	2	4	PT/NI1000	2 relays	2
TCI-C25-0	40-11 0068	24 VAC	Schedules	2	4	PT/NI1000	2 TRIAC	2

Temperature sensors: Use Vector Controls NTC or PT1000/NI1000 sensors to achieve maximum accuracy: SDB-Tn10-20 (duct), SRA-Tn10 (room), SDB-Tn10-20 + AMI-S10 as immersion sensor for NTC (used with TCI-C11, TCI-C13 and TCI-C22). SDB-Tp2-20 (duct), SRA-Tp2 (room), SDB-Tp2-20+AMI-S10 (immersion), SOD-Tp2 (outdoor) for PT1000 used with TCI-Cx4 and TCI-Cx5.

Actuators: Choose modulating actuators with an input signal type of 0-10 V DC or 4-20 mA (min. and max. signal limitations may be set with parameters. 3-pointpoint actuators with constant running time are recommended.

Binary auxiliary devices (e.g. pumps, fans, on/off valves, humidifiers, etc.): Do not directly connect devices that exceed specified limits in technical specifications – observe startup current on inductive loads.

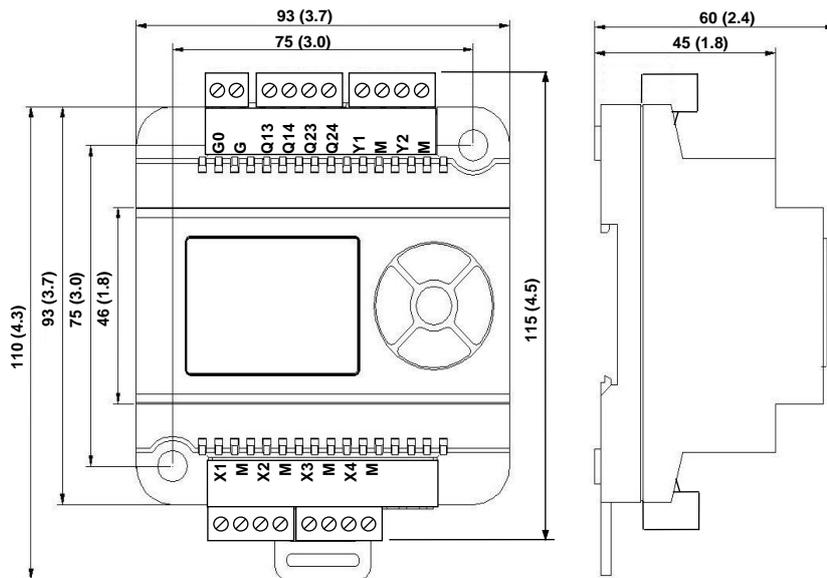
Technical specifications

Warning! This device is intended to be used for comfort applications. Where a device failure endangers human life and/or property, it is the responsibility of the owner, designer and installer to add additional safety devices to prevent or detect a system failure caused by such a device failure. The manufacturer of this device cannot be held liable for any damage caused by such a failure.

Failure to follow specifications and local regulations may endanger life, cause equipment damage and void warranty.

Power supply	Power requirements	24 VAC ±10%, 50/60 Hz, 24 VDC ±10% SELV to HD 384, Class II transformer, 48 VA max.	
	Power consumption	Max. 3 VA	
	Electrical connection	Removable terminal connectors, wire 0.34...2.5 mm ² (AWG 22...13)	
	Clock backup	Min. 48 hours	
Signal inputs	Universal input Inputs signal Resolution	Input configured for voltage or current 0...10 V or 0...20 mA 9.76 mV or 0.019 mA (10 bit)	
	Passive input	Input configured to remote temperature (RT) or digital input (DI)	
	TCI-C11, TCI-C15, TCI-C22 Type & range:	NTC (Sxx-Tn10): -40...140 °C (-40...284 °F)	
	TCI-C14, TCI-C15, TCI-C24, TCI-C25 Type & range:	PT1000 (Sxx-Tp2): -50...205 °C (-58...401 °F) NI1000 (Sxx-Tk5): -50...180 °C (-58...356 °F)	
Signal outputs	Analog outputs Output signal Resolution Maximum load	DC 0...10 V or 0...20 mA (500 Ω max.) 9.76 mV resp. 0.019 mA (10 bit) 20 mA, 250 Ω max.	
	Relay outputs AC voltage DC voltage	TCI-C11, TCI-C22, TCI-C14, TCI-C24 0...250 VAC, 5 (3) A max. each output 0...30 VDC, 5 (3) A max. each output	
	TRIAC outputs AC voltage	TCI-C13, TCI-C15, TCI-C25 24...250 VAC, 3A max., 250 VA max. each output	
	Insulation strength between relays or TRIAC contacts and system electronics: between neighboring contacts:	3750 V AC to EN 60 730-1 1250 V AC to EN 60 730-1	
	Environment	Operation Climatic conditions Temperature Humidity	To IEC 721-3-3 class 3K5 0...50 °C (32...122 °F) <95 % RH non-condensing
		Transport & storage Climatic conditions Temperature Humidity Mechanical conditions	To IEC 721-3-2 and IEC 721-3-1 class 3K3 and class 1K3 -25...70 °C (-13...158 °F) <95 % RH non-condensing class 2M2
		Standards	 conformity EMC directive Low voltage directive
Product standards Automatic electrical controls for household and similar use			EN 60 730 -1
Special requirement on temperature dependent controls			EN 60 730 - 2 - 9
Electromagnetic compatibility for industrial and domestic sector	Emissions: EN 60 730-1 Immunity: EN 60 730-1		
Degree of protection	IP30 to EN 60 529 if mounted correctly		
Pollution class	II (EN 60 730-1)		
Safety class:	III (IEC 60536) if SELV is connected to DO II (IEC 60536) if line voltage is connected to DO. Local regulations must be observed!		
Overvoltage category	III (EN 60 730-1)		
General	Cover, back part		Fire proof ABS plastic (UL94 class V-0)
	Dimensions (H x W x D)		60 x 93 x 115 mm (2.4 x 3.7 x 4.5) inch
	Weight (including package)		TCI-C11, TCI-C14: 280g (9.9oz) TCI-C13, TCI-C15, TCI-C22, TCI-C24: 295 g (10.4 oz) TCI-C25: 305 g (10.8 oz)

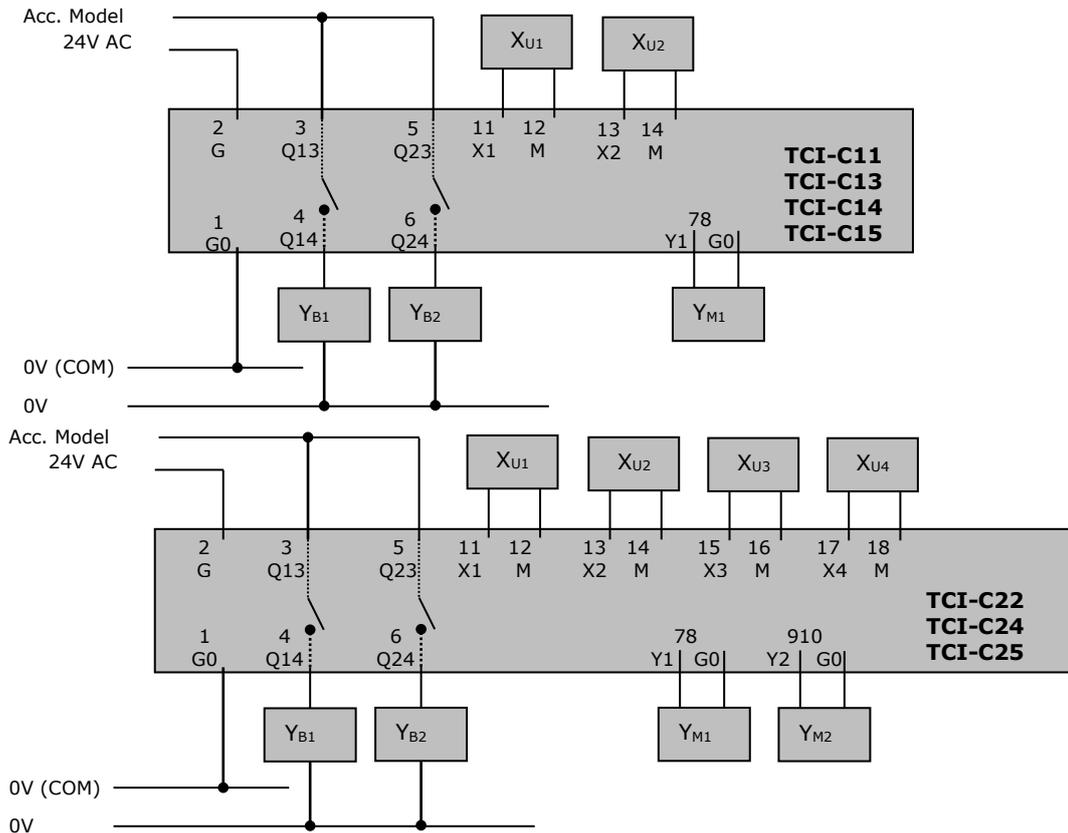
Dimensions, mm (inch) and installation



- Mount in standard cabinet to DIN 43880
- Surface mount to top-hat rail to EN 60715
- Surface mount with 2 #4 screws.
- A protective housing must be used if mounted outside an electrical cabinet.
- Ensure adequate air circulation to dissipate heat generated during operation.
- Observe local regulations.
- Do not mount in a wet or condensation prone environment.

See installation sheet no. 70-000537 (www.vectorcontrols.com)

Connection

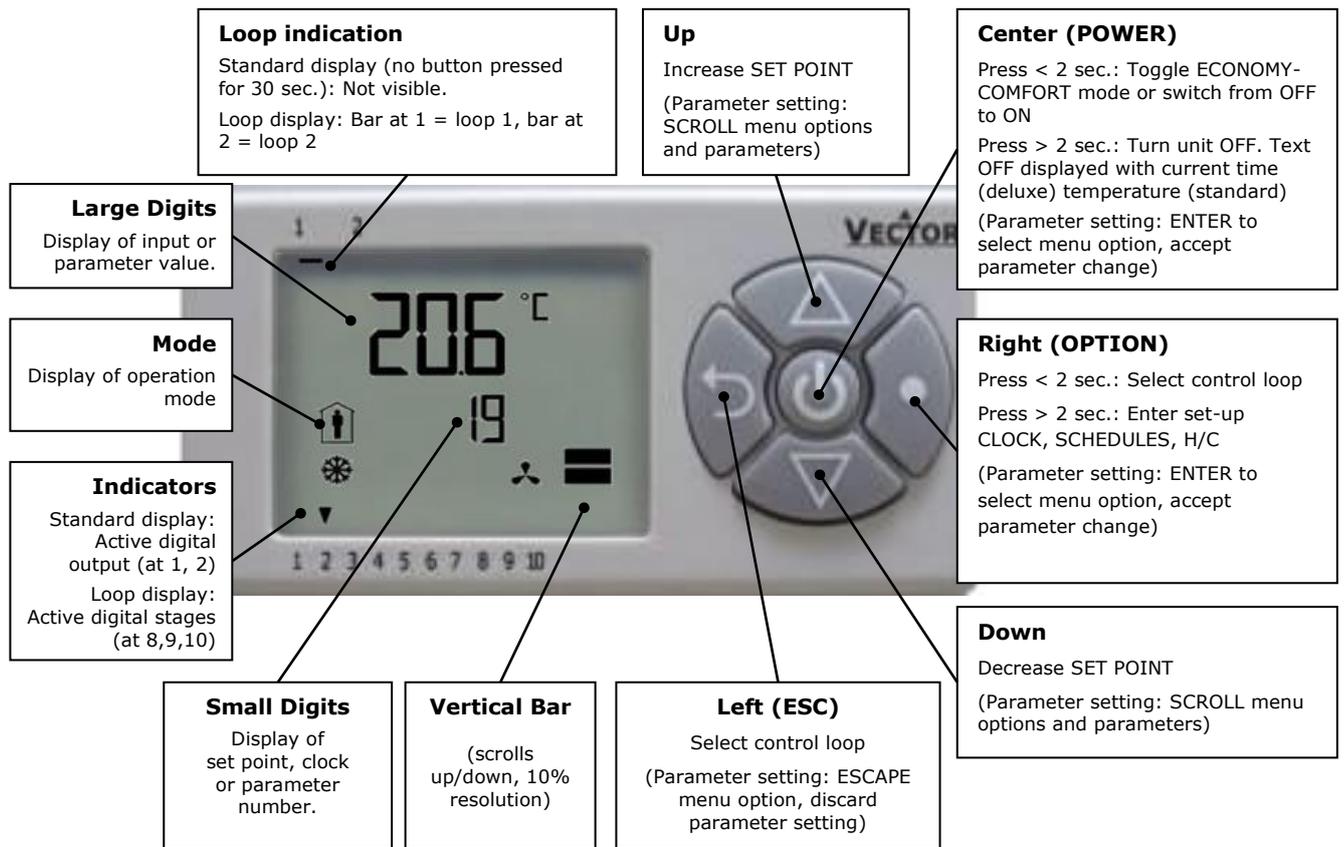


Terminal description

G0	Power supply:	0 V, -24 VDC; common for power supply, analog outputs
G	Power supply:	24 VAC, +24 VDC
M	Signal ground:	Common for universal inputs. Internally connected to G0
Q..	Binary outputs:	Potential free switching contacts, relays or TRIAC depending on type
X..	Universal input:	NTC 10kΩ or PT1000/Ni1000 depending on type, 0...10 V or 0...20 mA
Y..	Analog output:	0...10 V or 0...20 mA

Use copper, twisted pair, conductors only. The operating voltage must comply with the requirements for safety extra-low voltage (SELV) as per EN 60 730. Use safety insulating transformers class II with double insulation as per EN 60 742; they must be designed for 100% ON-time. When using several transformers in one system, the connection terminal 1 must be galvanically connected. TCI is designed for operation of AC 24 V safety extra-low voltage and is short-circuit-proof. Supplying voltages above AC 24 V to low voltage connections may damage the controller or other devices. Connection to voltages exceeding 42 V endangers personnel safety.

Display and operation



Operation mode symbols		Control symbols	
	Comfort (occupied): All control functions operating per set points		Heating (reverse) active
	Economy (unoccupied): Set points shifted according to 1L07, 2L07		Cooling (direct) active
OFF	Energy hold off: Outputs are off, inputs monitored for alarms		Schedule set
			Manual override
			Fan active

Standard display (parameters UP08, UP09, UP10)

- Active when no key has been pressed for 30 seconds.
- Contents may be chosen with parameters.

Loop display

- Active when changing set points. Large digits show input value. Small digits show set point. Vertical bars show analog output value. Arrows on 8, 9, 10 show binary (digital) output stages.

Override of secondary set point in cascade control

- If cascade control is active (with VAV for example) the user can override the primary loop and manually select the set point of the secondary loop (the loop is now changed to CAV). Typically for tuning the VAV system. This feature may be disabled with UP02.
- While the secondary loop is displayed change the set point with UP/DOWN. Override cascade symbol appears.
- Press OPTION to move back to the temperature loop and cancel cascade override.

Power failure

- All parameters and set points are memorized and do not need to be re-entered.
- Upon return of power: Set *parameter UP05* to keep the unit off, switch on, or operation mode before power failure.
- Clock and time schedule settings retained for 48 hours (after powered for at least 10 hours).

Error messages

Err1: An assigned input is not enabled or missing. All control loops, functions and outputs tied to this input will be disabled. Verify input connections, jumper settings and parameter settings for the input involved.

Err3: A function refers to a disabled input. Disable the function or enable the input.

Err4: Internal failure. Product must be replaced.

Manual heat – cool change

To manually change heating or cooling mode press the OPTION key for more than 2 seconds. Access to manual heat – cool change may be disabled by parameters.

<p>For TCI-C11: Press OPTION > 2 sec. SEL and H-C is displayed. For TCI-C22: Press OPTION > 2 sec. SEL and current time is displayed. Press UP key twice. SEL and H-C is displayed. Press OPTION again to toggle H or C.</p>	<p>SEL H-C </p>
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Display input values

<p>For TCI-C11: Press OPTION > 2 sec. SEL and H-C is displayed. Press UP key once: UI1 and its value are displayed For TCI-C22: Press OPTION > 2 sec. SEL and current time is shown. Press UP key three times. UI1 and value are displayed.</p> <p>Press UP key again to step through the next active input Note: disabled inputs will not be shown.</p>	<p>75% UI 1</p>
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Clock operation

TCI-C2x contains a quartz clock with battery back-up (not available in TCI-C1x). Up to 8 mode changes based on time and day of the week may be programmed. Also position an output or select a set point directly with a time schedule. A blinking clock indicates that the time has not been set or if the unit was without power for longer than 48 hours. The time needs to be set to allow time schedules to operate.

Clock setup

<p>Press OPTION > 2 sec. SEL and current time displayed Press OPTION < 2 sec. to change time, Minutes blink: UP/DOWN to changes, OPTION to save, Hours blink: UP/DOWN to changes, OPTION to save, Press OPTION to save time, DAY1 blinks: UP/DOWN to change, OPTION to save</p>	<p>SEL 00:00 DAY1 (Mon)</p>
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Enable/disable time schedules

<p>Press OPTION > 2 sec. SEL and current time displayed Press UP: SEL and PRO displayed, clock symbol blinks Press OPTION: Time schedule status displayed OFF or ON: Press OPTION OFF/ ON blinks, UP/DOWN to change, OPTION to save</p>	<p>SEL PRO </p>	<p>Pro OFF/ON</p>
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Creating time schedules

Step 1: Select a switching time (Up to 8, Pr01–Pr08)

<p>Press UP while PRO-ON displayed: Large digits display Pr01, small digits display 00:00 Press OPTION:00:00 blinks Press UP/DOWN to select Pr01switching time from 00:00–23:45 Press OPTION to save switching time (bar appears indicating step 1 complete):DAY 1 blinks</p>	<p>Pr01 08:00</p>	
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Step 2: Apply selected switching time (Pr01) to DAY1 (Mon) – DAY 7 (Sun)

<p>While Pr01 is displayed and DAY1 is blinking: Press UP: Activate Pr01 switching time for DAY1 (triangle appears on 1), Press DOWN: Deactivate Pr01 switching time for DAY1(triangle disappears) Press OPTION to save Pr01 DAY1 (2nd bar indicates step 2 complete): Repeat for DAY2 – DAY7</p>	<p>Pr01 DAY1 ▼ 1 2 3 4 5 6 7</p>	
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Step 3: Select action for switching time (Pr01+Days)

<p>After Pro1, DAY1–DAY7 is completed (pro1 switching time activate or deactivate on desired days), press OPTION again to come to desired action for Pro1. The following options appear in order: No = switching time not active OP = operation mode (select ON (comfort/occupied), ECO (economy/unoccupied), OFF) L1 = set point of loop 1 (select set point) L2 = set point of loop 2 (select set point) d1 = ON/OFF status of do1 (output must be in manual mode) d2 = ON/OFF status of do2 (output must be in manual mode) A1 = set point (0-100%) of AO1 (output must be in manual mode) A2 = set point (0-100%) of AO2 (output must be in manual mode) After repeatedly pressing OPTION through DAY7: First available action no appears, blinking: Press UP/DOWN to scroll through the 8 possible actions (3rd bar indicates step 3 complete)</p>	<p>Pr01 no</p>	
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Step 4: Complete switching event (e.g. Pr01 = 08:00, DAY 1, comfort mode)

<p>Available actions blink as you scroll through them, press OPTION to select one: Characteristics of action (e.g. 0–100% for A1) appear (4th bar indicates step 4 complete) Press UP/DOWN to select, OPTION to complete</p>	<p>Pr01 08:00</p>	
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Setting parameters to configure the controller

TCI is an intelligent controller with the flexibility to fit a wide range of applications. The control operation is defined by parameters set using the standard operation terminal. There are two levels:

1. **User/display parameters (password 0009)**
2. **Control parameters (password 00241)**

Recommended set-up procedure:

1. **Set jumpers on the back of the controller for inputs and outputs**
2. **Connect power supply and inputs**
3. **Make sure Celsius – Fahrenheit settings are correct (UP07)**
4. **Program input parameters**
5. **Program control parameters**
6. **Program output parameters**
7. **Program auxiliary functions and user settings**
8. **Test function of unit**
9. **Switch off power**
10. **Connect outputs**
11. **Test control loop**

Parameters are grouped according to modules:

Module	Description	PW
UP	User and display parameters	009
UI	Input configuration: 1U, 2U, 3U, 4U	241
LP	Control loops Lp1, Lp2	
AO	Analog output configuration, AO1, AO2	
DO	Binary output configuration, DO1, DO2	
FU	Special functions	

How to change parameters

1. Press UP/DOWN buttons simultaneously for three seconds. The display will show firmware version and revision number. Press the OPTION button to start login.
2. CODE is shown in small display.
3. Code to access user parameters is 009, control parameter is 241. The access numbers are fixed and cannot be changed.
4. Select this using UP/DOWN buttons.
5. Press OPTION after selecting the correct code.
6. Once logged in with 009, the user/display parameters are displayed immediately. Once logged in with 241 control modules are displayed (Lp1, Lp2, 1u, 2u, etc.) –select with UP/DOWN and open with OPTION. As soon as the module is open its parameters are displayed.
7. Select the parameters with the UP/DOWN buttons. Change a parameter by pressing the OPTION button. Three arrows are displayed to indicate that the parameter may be modified. Use UP/DOWN buttons to adjust the value.
8. After you are done, press OPTION to save the new value and return to the selection level (arrows disappear when selection is saved). Pressing left hand POWER button without pressing OPTION will discard the value and return without saving. For control parameters press POWER again to leave parameter selection and return to control module selection.
9. Press the POWER to leave the menu. The unit will return to normal operation if no button is pressed for more than 5 minutes.

User and display parameters (password 009)

Parameter	Description	Range	Default		
UP 00	Enable access to operation modes	ON/OFF	ON		
UP 01	Enable access to set points	ON/OFF	ON		
UP 02	Enable manual control in cascade	ON/OFF	ON		
UP 03	Enable change of heating/cooling mode for 2 pipe systems	ON/OFF	ON		
UP 04	Enable access to time programs:	ON/OFF	ON		
UP 05	State after power failure: 0= OFF, 1= ON, 2= state before power failure	0, 1, 2	2		
UP 06	Enable economy (unoccupied) mode. Shift the set point to a lower temperature in winter or higher temperature in summer in order to save energy. Economy mode may be activated through the POWER button, or with the external input (typically for key card switches in hotel rooms or motion detectors for meeting rooms.)	ON/OFF	ON		
UP 07	Celsius or Fahrenheit: ON= Fahrenheit, OFF= Celsius	ON/OFF	OFF (Celsius)		
UP 08	Show standard display while no key is pressed	ON/OFF	ON		
UP 09	Select type of content for large digits (00= OFF):		0-5	1	
	01= Input 02= Set point 03= Analog output	04= Binary output 05= Clock			
UP 10	Select content source for large digits (0=OFF):				
	Input: 1= 1U 2=2U 3= 3U 4= 4U	Set point: 1= Lp1 2= Lp2	Analog output: 1 = AO1 2 = AO2 3 = FO1	Binary output: 1 = DO1 2 = DO2	0-4
UP 11	Select type of content for small digits(same options as UP09)	0-5	Standard = 2 Deluxe = 5		
UP 12	Select content source for small digits (same options as UP10)	0-4	1		
UP 13	Select analog output for vertical bar display (00= OFF):		0-5	4	
	01= AO1 02 = AO2 03 = FO1	04= Output LP1 05= Output LP2			
UP 14	Display heating/cooling state in standard display mode	ON/OFF	OFF		
UP 15	ON = Alarms blink after being active and need to be confirmed OFF= Alarms are only shown when they are active	ON/OFF	ON		
UP 16 (TCI-C2x)	Clock display type: OFF= 24-hr, ON= 12-hr(AM/PM)	ON/OFF	OFF (24 hr)		
UP 17 (TCI-C2x)	Reset timer for manual override of PRO time schedule: 0= Not active 1-255= Delay for controller to go back to the scheduled Energy Hold OFF, ECONOMY, or COMFORT operation mode if the operation mode is changed manually.	0-255 Min	60 (min.)		

Control configuration (password 241)

Input configuration

Universal inputs 1U, 2U, 3U, 4U (analog, binary or passive temperature)

1U 00	Signal type (0= not active): 1=0-10 V or 0-20 mA, 2=2-10 V or 4-20 mA, 3= NTC or PT1000, 4 = NI1000 Note: PT1000 and NI1000 are only available on TCI-Cx4 and TCI-Cx5	0-3 0-4	1
1U 01	Display minimum value	-50-205	0
1U 02	Display maximum value	-50-05	100
1U 03	Analog input display range: 0= x 0.1, 1= x 1, 2= x 10, 3 = x 100	0-3	1
1U 04	Analog input unit of measure: 0= no unit, 1= %, 2= °C /°F, 3= Pa	0-3	0
1U 05	Sensor sampling rate(control speed decrease as rate increases)	0-100	3
1U 06	Sensor calibration	Per input	0
1U 07	Alarm 1 low limit enable	OFF/ON	OFF
1U 08	Alarm 1 low limit value	-40-215 °C	5 °C(40 °F)
1U 09	Alarm 2 high limit enable	OFF/ON	OFF
1U 10	Alarm 2 high limit value	-40-215 °C	50 °C (122 °F)
1U 11	Hysteresis alarm 1 and 2	0-100 °C	5 °C(10 °F)
1U 12	Calculate a range of inputs (0=not active): 1= average, 2= minimum, 3= maximum, 4= differential	0-4	0

- ➔ Set jumpers on the back of the controller: 0-10 VDC (default), 0-20 mA, or RT/DI (passive temperature or binary)
- ➔ Further define analog inputs with U00
- ➔ Passive temperature input may be NTC 10k or PT1000/NI1000 depending on controller type used. TCI-C11, TCI-C13, TCI-C22 use NTC, TCI-C14, TCI-C15, TCI-C24 use PT1000/NI1000.
- ➔ Match sensor range to input display. With a differential pressure transmitter having 0-200 Pa measuring range set U01 display minimum to 0 and U02 display maximum to 200. The allowable range value of -50-205 may be adjusted with multipliers inU03. The largest displayable values are -990-9999. Limiting range increases resolution. Applies to analog as well as passive temperature inputs.
- ➔ For binary input (open/close contact) set the jumper to RT/DI and parameter U00 to an analog input. An open contact reads as a high value (100%), a closed contact as a low value (0%).
- ➔ Enable / Disable an alarm. Setting the alarm enable to OFF will prevent the alarm from being displayed on screen. It may never the less be used to control an output by setting the appropriate output alarm flags. This way, an alarm limit may be used as interlock.
- ➔ Specify the input value that triggers an alarm. Hysteresis is the difference between alarm level input and value required to turn the alarm off. An alarm is displayed as text if enabled (see table). Alarm text can be set to blink continuously until acknowledged by pressing the OPTION button or only while the alarm conditions are active (see user parameter UP15).

Input	1U	2U	3U	4U
Low limit	ALA1	ALA3	ALA5	ALA7
High limit	ALA2	ALA4	ALA6	ALA8

- ➔ Calculate mathematical functions over multiple inputs for loop control or display with xU12. In order to calculate average, minimum or maximum between several inputs, make sure all the inputs are of identical type and range and then activate the same function on xU12 on all the selected inputs. The largest input of the group selected will carry the calculated value. For example: When average is activated on 2U12 and 1U12 = 1, the average is carried on UI2. UI2 may now be used as input for control loops and it will show the average value of UI1 and UI2 combined. It is possible to use different functions on different inputs. For example: minimum of UI1 and UI3 and maximum of UI2 and UI4.
- ➔ The differential function may only be calculated on subsequent inputs. Such as UI2-UI1. The function must only be activated on the minuend (UI2 in this example). The displayed value of the minuend will change into the difference: UI2 in - UI1 = UI2 out. It is possible to have multiple differentials on one controller. It is not possible to reverse the subtraction to UI1-UI2.

Control loop configuration

Manipulation of the set point (1L, 2L)

Parameter	Description	Range	Default
1L 00	Select loop control input (0= loop disabled): 1= 1U, 2= 2U, 3= 3U, 4= 4U	0-4	1
1L 01	Minimum set point limit heating	per input	10 °C (50 °F)
1L 02	Maximum set point limit heating	per input	28 °C (82 °F)
1L 03	Minimum set point limit cooling	per input	18 °C (64 °F)
1L 04	Maximum set point limit cooling	per input	34 °C (92 °F)
1L 05	Enable set point compensation (0= disabled) 1= winter compensation, 2= summer compensation, 3= winter and summer	0-3	0
1L 06	Loop input special (0= normal): 1= combine loop 1 and loop 2 2= cascade with reverse sequence of primary loop 3= cascade with direct sequence primary loop 4= cascade with both reverse and direct sequence of primary loop	0-4	0
1L 07	Economy mode set point shift: (Function depends on 1L25) The comfort (occupied) set point is shifted by the value set with parameter. Reduces the heating set point and increases the cooling set point.	per input	5.0 °C (10 °F)
1L 08	Dead zone between heating and cooling set points The dead zone span lies between the heating and the cooling set point. The output is off while the measured value is within the dead zone span. A negative dead zone is not possible.	Per input	1.0 °(2 °F)
1L 25	Fixed set point in ECONOMY mode OFF = Set point is shifted according to value in 1L07 ON = Shift to min. set point heating, max. set point cooling	ON, OFF	OFF
1L 26	Define winter/summer set point compensation range. 0 = Temperature setback: shift to set point limits	Acc. input	0.0 °C

→ Economy mode set points: There are two possibilities to change the set point in economy mode: Shift it by L07 or switch to the minimum set point limit in heating mode and maximum set point limit in cooling. Economy mode may be disabled by setting UP06 to OFF.

→ Control loops and sequences are activated when output parameters are defined.

→ Cascade control

In cascade control (L06) the set point of the secondary loop is determined by the demand of the primary loop. The set point of the secondary loop is calculated proportionally according to demand of the primary loop between minimum and maximum set point limits. Cascade control is activated by setting the parameter XL06 of the secondary control loop.

A typical application is a variable air volume system where the temperature output determines the pressure set point.

Cascade control example – VAV application

Primary loop = temperature (1L)	Secondary loop = airflow/pressure (2L)
	Settings: 2L01=20%, 2L02=60%, 2L06=2
Depending on temperature set point, the demand is calculated for loop 1. For example 40%.	Based on demand of loop 1, the set point of pressure loop is calculated proportionally between min (20%) and max (60%) pressure set point limits. A demand of 40% will result in a set point of 36% in the above example.

→ Set point compensation

The set point compensation is typically used to compensate the set point due to a change in outside temperature. The relationship to the input used to drive the set point compensation is defined in auxiliary functions FU00 to FU07.

→ Enable summer or winter set point compensation for this control loop with L05. Define the compensation range with L26. L26 defines the full set point shift once the compensation input has reached its lower limit in winter mode or upper limit in summer mode.

Setting the range parameter to 0 will activate the set point setback function: The setback function shifts the set point toward the set point minimum or the set point maximum based on an external input value. Once the compensation input has reached its lower limit in winter mode or upper limit in summer mode, the set point is fixed to the set point minimum or maximum value. Commonly this is used for humidity control to avoid condensation on outside walls or windows in very cold weather.

PI control sequence

Parameter	Description	Range	Default
1L 09	Offset for heating PI sequence	per input	0
1L 10	Offset for cooling PI sequence	per input	0
1L 11	P-band heating	per input	2.0 °C (4.0 °F)
1L 12	P-band cooling	per input	2.0 °C (4.0 °F)
1L 13	Integral gain heating (0.1 steps) low= slow reaction, high= fast reaction	0-25.5	0.0
1L 14	Integral gain cooling (0.1 steps)	0-25.5	0.0
1L 15	Measuring interval integral (seconds) low= fast reaction, high value= slow reaction	0-255	1 sec.

→ **Proportional control(P-band)**

The proportional control function calculates the output based on the difference between set point and measured value. The proportional band (P-band) defines the difference between set point and measured value which will result in a 100% output. For example, with a heating or reverse 0-10 V control sequence, and a 2.0 °C (4.0 °F) P-band value, at 10 V the controller will be 2.0°C (4.0°F) below set point. This is the working range of the proportional control sequence.

Setting the proportional band to 0 disables proportional control.

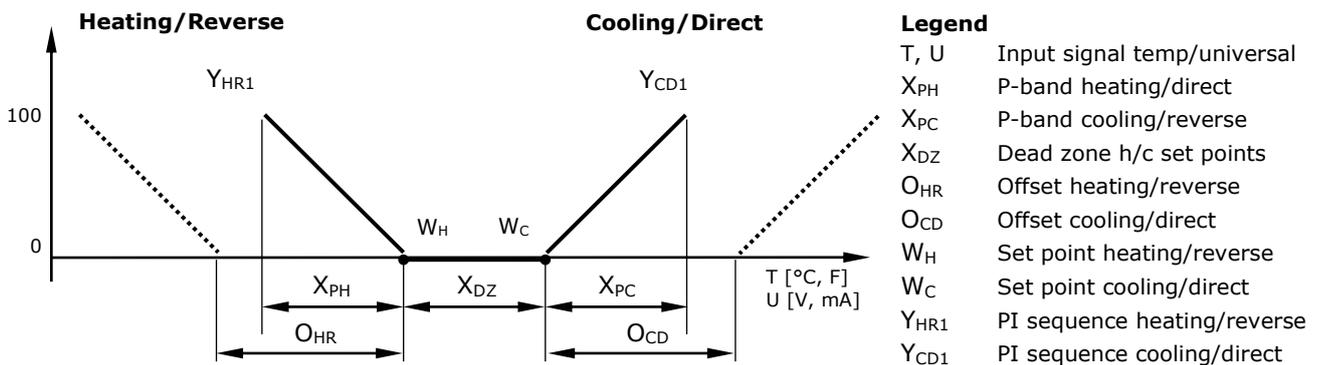
→ **Integral and differential control**

Proportional control is in most cases a very stable control mode. The flaw of proportional control alone, however, is that the set point is normally not reached. As the measured value gets closer to the set point, the output reduces until it reaches a point, a fraction above or below the set point, where the output equals the load. To reach the set point and achieve a higher level in comfort the integral/differential function should be activated.

Integral Gain (KI) dynamically increases the output by the selected KI value every **Measuring Interval TI** until the set point is reached. The challenge is to prevent hunting, where the output increases too fast, the temperature overshoots the set point, the output goes to 0, the temperature undershoots the set point, and the cycle repeats itself. Hunting may result if the integral gain is too high or measuring interval too short. Each system is different. To prevent instability the P-band should be extended when integral gain is active (L14 or L15 set above 0).

Setting the integral gain to 0 disables integral and differential control.

Recommended values						
	heating (air)	heating (radiant)	humidifying	cooling	dehumidifying	pressure
P-band	2-3°C(4-6°F)			1-1.5°C(2-3°F)		
Measuring interval (TI)	2	5	15	1	70	1
Integral gain (KI)	0.2	0.1	0.1	0.2	0.3	0.8



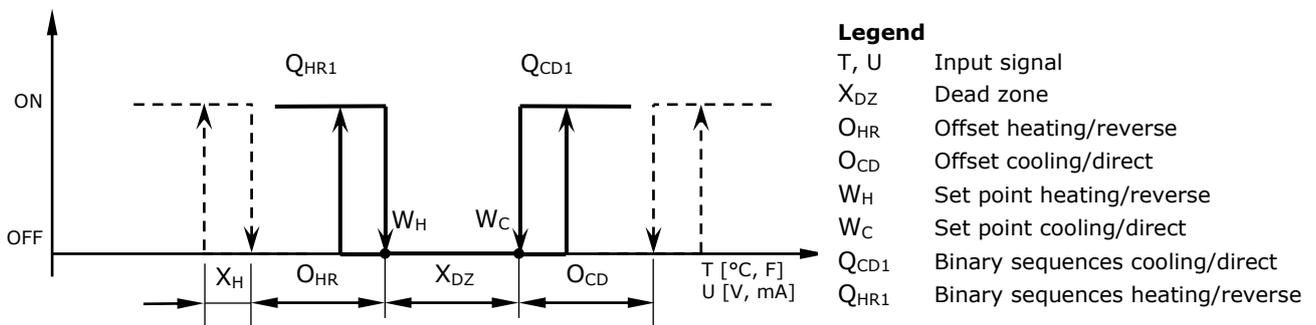
Digital control sequence

Parameter	Description	Range	Default
1L 16	Action of stages: 0= cumulative: stage 1 stays on when 2 on comes on 1= single: stage 1 turns off when 2 on comes on 2= digital: stage 1 only, stage 2 only, then stage 1 plus 2	0-2	0
1L 17	Offset for heating/reverse binary sequences	per input	0.0°(0.0°F)
1L 18	Offset for cooling/direct binary sequences	per input	0.0°(0.0°F)
1L 19	Switching span heating	per input	1.0°(2.0°F)
1L 20	Switching span cooling	per input	1.0°(2.0°F)
1L 21	Switching hysteresis	per input	0.5°(1.0°F)
1L 22	Switching delay	0-255s	10s
1L 23	Activation of reverse/direct (heat/cool) sequence OFF= activates based on demand ON = follows heat/cool state of controller: Set manually or by auxiliary function (FU20-FU23)	ON/OFF	OFF
1L 24	Delay for heat /cool changeover when L23=OFF	0-255 min	5 min

→ Cumulative stage action (L16=0) is typically used in electric heat applications, and single stage action (L16=1) in fan speed applications. Digital stage action (L16=2) is especially useful in electric heat applications to generate three steps with just two outputs. For example: Step 1=100W, step 2=200W, step 3=300W.

	Cumulative	Single	Digital
Stage 1	Q ₁	Q ₁	Q ₁
Stage 2	Q ₁ +Q ₂	Q ₂	Q ₂
Stage 3			Q ₁ +Q ₂

- Switching hysteresis (L21) is the difference between switching on and switching off. A small hysteresis will increase the number of switching cycles and thus the wear on associated equipment.
- With switching delay (L22) cumulative stages will not switch on simultaneously. With a sudden demand or initial power stage 2 will not start earlier than 10 seconds (default value) after stage 1 has been initiated.



Output configuration

Analog output configuration (1A, 2A)

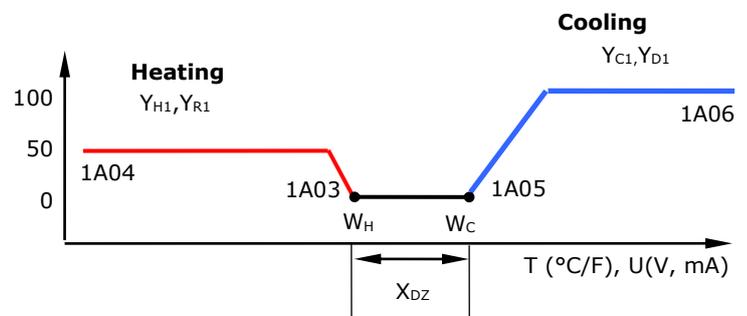
Parameter	Description	Range	Default
1A 00	Select control loop or special function (0= OFF): 1= LP1, 2= LP2 3= Dehumidify (4 pipe, max LP1 cooling, LP2 direct) 4= Manual positioning or by time schedule (0-100%) 5= Feedback: transmit value of an input	0-5	1
1A 01	When A00=1 or 2 select sequence or set point feedback: 0= Heating/reverse 1= Cooling/direct 2= Heating and cooling (2 pipe) 3= Transmit set point of selected control loop When A00 = 4 select manual/time schedule positioning 0 = Position output by time schedule only 1 = Position output manually or by time schedule When A00=5, select input (0= function disabled): 1= 1U, 2= 2U, 3= 3U, 4= 4U	0-4	0
1A 02	Type of output signal: OFF= 0-10V, 0-20mA, ON= 2-10V, 4-20mA	ON/OFF	OFF
1A 03	Minimum limitation of output signal default and in loop heating mode	0-100%	0
1A 04	Maximum limitation of output signal default and in loop heating mode	0-100%	100%
1A 05	Minimum limitation of output signal in loop cooling mode	0-100%	0%
1A 06	Maximum limitation of output signal in loop cooling mode	0-100%	100%
1A 07	Choose alarm to set output to 100% (output 0% on conflicting alarms) ▽▽▽▽▽▽▽▽ Alarm: 1 2 3 4 5 6 7 8	Triangle shown =alarm selected	▽▽▽▽▽▽▽▽
1A 08	Choose alarm to set output to 0%. (output 0% on conflicting alarms) ▽▽▽▽▽▽▽▽ Alarm: 1 2 3 4 5 6 7 8	Triangle shown =alarm selected	▽▽▽▽▽▽▽▽
1A 09	Transmit value (1A00=5): minimum input value	per input	0°C
1A 10	Transmit value (1A00=5): maximum input value	per input	100°C

- ➔ Set jumpers on the back of the controller: 0-10 VDC (default), or 0-20 mA. Further define analog outputs with A02. Custom ranges can be created by setting minimum and maximum signal limits.
- ➔ A control loop, special function, digital control or analog control sequence is not active until it is assigned an output.
- ➔ Low and high limit alarms are defined with input parameters. With output parameters assign an alarm to an output and select output state. The required output for each alarm can be individually selected. Multiple alarms can be signed to one output. If one alarm is selected to simultaneously activate and deactivate an output, the one to de-activate has precedence.
- ➔ With manual positioning (1A00=4) position the output by time schedule or directly in 0.5% steps. Setting 1A01 to 0 will disable manual positioning. The output will then only be controlled by time schedule.
- ➔ With dehumidifying (1A00=3) the maximum value is taken of cooling and dehumidifying. When the humidity is too high, cooling will continue to operate, even without a demand for cooling, to dehumidify the air and heating will activate to maintain comfort.
- ➔ Input values of universal inputs and set points of control loops may be transmitted on the analog outputs.

Output Priority

1. Alarm level low
2. Alarm level high
3. Operation mode OFF
4. Control function

➔ For **VAV Function** individual minimum and maximum limits may be assigned for cooling and heating. In VAV applications maximum cooling output matches the maximum air volume the VAV box is set to deliver. As demand for airflow in cooling mode decreases, airflow dwindles until it reaches minimum cooling output (1A05). This minimum will be based on the airflow needed at design cooling and is typically 10% to 15% of maximum cooling airflow. When this minimum is reached the system is in dead-band – neither heating nor cooling. Minimum airflow in heating mode is set with 1A03. As the system moves into heating mode, heating airflow increases until it reaches the maximum heating output (1A04), typically 30 to 50% of maximum cooling airflow.



Digital output configuration (1d, 2d)
Settings for floating point outputs (1d00 or 2d00=ON)

Parameter	Description	Range	Default
1d 00	Enable digital or floating point output OFF= 1d and 2d are two digital outputs ON = 1d and 2d are one floating point output (1d open,2d close)	ON/OFF	OFF
1d 01	Select control loop or special function (0= OFF) 1= LP1, 2= LP2 3= Dehumidify (4 pipe, max LP1 cooling, LP2 direct) 4= Manual positioning or by time schedule (0-100%) 5= Controller state functions	0-5	0
1d 02	If d01=1 configure output: 0= Heating/reverse 1= Cooling/direct 2= Heating and cooling (2 pipe) If d01 = 4 select manual/time schedule positioning 0 = Position output by time schedule only 1 = Position output manually or by time schedule If d01=5 select state functions: 0= ON if controller operation state is ON 1= ON while demand on any output 2= ON while controller in heating mode and operation state ON 3= ON while controller in cooling mode and operation state ON	0-5	0
1d 03	Running time (from open to close)	0-255s	90s
1d 04	Switching difference for floating point signal	0-100s	5s
1d 05	Not used		
1d 06	Choose alarm to set output to 100% (output 0% on conflicting alarms) ▽▽▽▽▽▽▽▽ Alarm: 1 2 3 4 5 6 7 8	Triangle shown =alarm selected	▽▽▽▽▽▽▽▽
1d 07	Choose alarm to set output to 0% (output 0% on conflicting alarms) ▽▽▽▽▽▽▽▽ Alarm: 1 2 3 4 5 6 7 8	Triangle shown =alarm selected	▽▽▽▽▽▽▽▽
1d 08	Not used		
1d 09	Not used		

- ➔ Low and high limit alarms are defined with input parameters. With output parameters assign an alarm to an output and select output state. Each alarm's required output can be individually selected. Multiple alarms can be signed to one output. Should one alarm be simultaneously selected to activate and deactivate the output, the one to de-activate has precedence.
- ➔ With manual positioning (1d01=4) position the output directly (open/close).
- ➔ With dehumidifying (1d01=3) the maximum value is taken of cooling and dehumidifying. When the humidity is too high, cooling will continue to operate, even without a demand for cooling, to dehumidify the air and heating will activate to maintain comfort.
- ➔ For floating point outputs the running time of the actuator used needs to be specified with 1d03. Running time is defined as the time required for the actuator to run from fully open to fully closed and vice versa. Actuators with a fixed running time are recommended. Once fully open or fully closed the running time for the actuator is extended for a full run-time cycle. This will allow the actuator position to be synchronized in case it has been moved during off time or an actuator with variable running time was used. Use switching difference parameter 1d04, to reduce the switching frequency of the actuator. The actuator will only move if the difference to the current actuator position is larger than this parameter.
- ➔ State functions (1d01=5) activate the output based on certain conditions with or without a demand for heating or cooling, in either comfort or standby mode. In Energy Hold OFF mode (EHO) the output will be off.

Output priority

1. Alarm level low
2. Alarm level high
3. Operation mode OFF
4. Control function

Digital output configuration (1d, 2d)
Settings for digital outputs (1d00 or 2d00=OFF)

Parameter	Description	Range	Default
1d 00	Enable digital or floating point output OFF= 1d and 2d are two digital outputs ON = 1d and 2d are one floating point output (1d open,2d close)	ON/OFF	OFF
1d 01	Select control loop or special function (0= OFF) 1= LP1, 2= LP2 3= Dehumidify (4 pipe, max LP1 cooling, LP2 direct) 4= Manual positioning or by time schedule (on/off) 5= State functions	0-5	0
1d 02	If 1d01=1, configure output: 0= Stage 1 heating/reverse 1= Stage 1 cooling/direct 2= Stage 1 heating and cooling, reverse and direct 3= Stage 2 heating/reverse 4= Stage 2 cooling/direct 5= Stage 2 heating and cooling, reverse and direct If d01 = 4 select manual/time schedule positioning 0 = Position output by time schedule only 1 = Position output manually or by time schedule If d01=5, select state functions: 0= ON if controller operation state is ON 1= ON while demand on any output 2= ON while controller in heating mode and operation state ON 3= ON while controller in cooling mode and operation state ON	0-5	0
1d 03	Switch-off delay (time output active with no more demand) Delay is in seconds or minutes depending on d09	0-255	90sec
1d 04	Switch-on delay(time demand active before output on) In state mode 1d01=5 outputs disabled during switch-on delay Delay is in seconds or minutes depending on d09	0-255	5 sec
1d 05	Activate PWM, set cycle time, seconds (>0activates, 0 deactivates)	0-1650s	0s
1d 06	Choose alarm to set output to ON (output OFF on conflicting alarms) ▽▽▽▽▽▽▽▽ Alarm: 1 2 3 4 5 6 7 8	Triangle shown =alarm selected	▽▽▽▽▽▽▽▽
1d 07	Choose alarm to set output to OFF (output OFF on conflicting alarms) ▽▽▽▽▽▽▽▽ Alarm: 1 2 3 4 5 6 7 8	Triangle shown =alarm selected	▽▽▽▽▽▽▽▽
1d 08	Display fan symbol while active	ON/OFF	OFF
1d 09	Binary switching delays in minutes or seconds OFF = delays are in seconds, ON = delays are in minutes	ON, OFF	OFF

- ➔ Low and high limit alarms are defined with input parameters. With output parameters assign an alarm to an output and select output state. Each alarm's required output can be individually selected. Multiple alarms can be signed to one output. Should one alarm be simultaneously selected to activate and deactivate the output, the one to de-activate has precedence.
- ➔ With manual positioning (1d01=4) position the output directly (ON/OFF).
- ➔ With dehumidifying (1d01=3) the maximum value is taken of cooling and dehumidifying. When the humidity is too high, cooling will continue to operate, even without a demand for cooling, to dehumidify the air and heating will activate to maintain comfort.
- ➔ State functions (1d01=5) activate the output based on certain conditions with or without a demand for heating or cooling, in either comfort or standby mode. In Energy Hold OFF mode (EHO) the output will be off.
- ➔ Pulse width modulation (PWM) mode is enabled with 1d05. In PWM mode the digital output will be switched on/off once per cycle. The on and off times are calculated according to the PI settings of the respective control sequence (see control loop Parameters L09-L15). TCI-C11 and TCI-C22 use relays for the digital outputs. It is not recommended to use cycle times below 100 seconds as the lifetime of the relays will be shortened with frequent switching. For PWM applications requiring cycle times below 100 seconds we recommend using TCI-C13 with TRIAC outputs.

Output priority

1. Alarm level low
2. Alarm level high
3. Operation mode OFF
4. Control function

Auxiliary functions

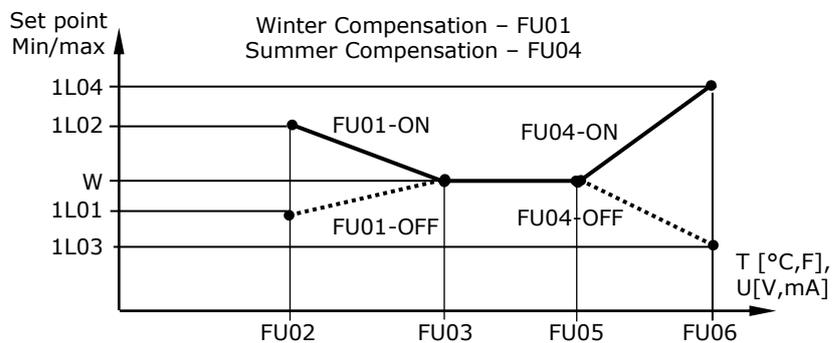
Summer/winter compensation

Parameter	Description	Range	Default
Fu 00	Select compensation input (0= function disabled): 1= 1U, 2= 2U, 3= 3U, 4= 4U	0-4	0
Fu 01	Winter compensation set point setback OFF= shift toward minimum set point heating (Loop parameter L01) ON= shift toward maximum set point heating (Loop parameter L02)	ON/OFF	OFF
Fu 02	Winter compensation lower limit (end of shift)	per input	5 °C (41 °F)
Fu 03	Winter compensation lower limit (beginning of shift)	per input	20 °C (68 °F)
Fu 04	Summer compensation set point setback OFF= shift toward minimum set point cooling (Loop parameter L03) ON= shift toward maximum set point cooling (Loop parameter L04)	ON/OFF	ON
Fu 05	Summer compensation lower limit (start of shift)	per input	35 °C (95 °F)
Fu 06	Summer compensation upper limit (end of shift)	per input	40 °C (104 °F)
Fu 07	Show hot/cool symbol while compensation active	ON/OFF	OFF

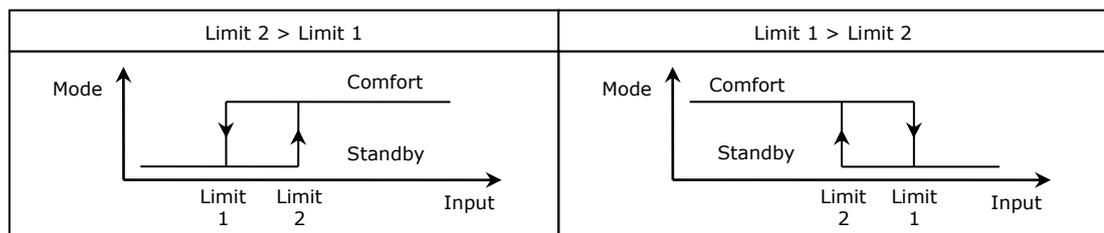
Comfort/economy mode changeover

Fu 08	Select comfort/economy changeover input (0= disabled): 1= 1U, 2= 2U, 3= 3U, 4= 4U	0-4	0
Fu 09	Economy activation delay (seconds)	-1275s	300s
Fu 10	Input limit 1	per input	10
Fu 11	Input limit 2	Per input	90

- Summer/winter compensation changes the set point due to a change in an input value, typically, but not limited to, an outdoor temperature input. Winter compensation starts when outside temperature drops below the upper limit of winter compensation (FU03). At maximum winter compensation the actual set point will be equal to the control loop's maximum heating set point (L02). Summer compensation starts when outside temperature exceeds the lower limit for summer compensation (FU05). At maximum summer compensation the actual set point will be equal to the control loop's maximum cooling set point (L04). Activate summer/winter compensation with control loop configuration parameter (L05).



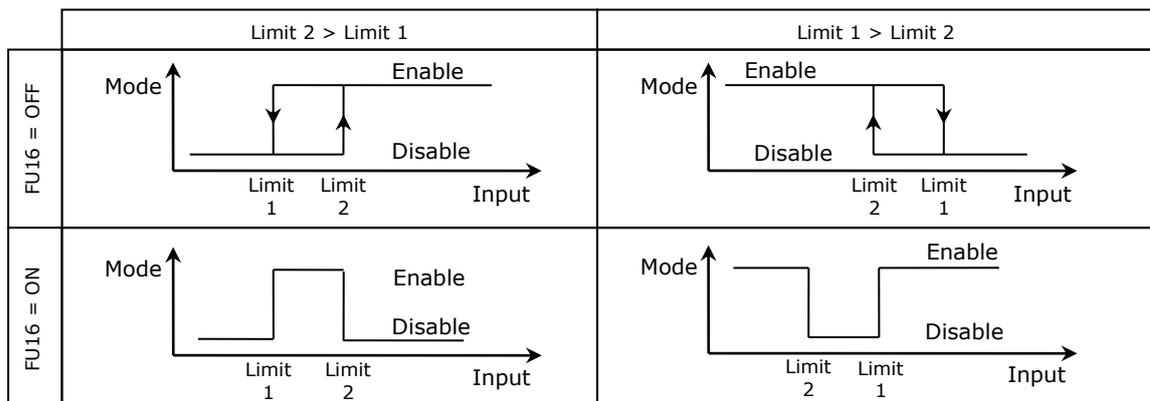
- Use comfort/economy mode changeover with key card switches, occupancy sensors, etc. Set input limit 1 and 2 with possibilities below. Example: When Limit 2 is greater than Limit 1, switch comfort-to-economy at the lower value, economy-to-comfort at the higher value. Activate comfort/economy changeover with loop configuration parameter(L07).



Enable/disable

Parameter	Description	Range	Default
Fu 12	Select enable-disable input (0=function disabled): 1= 1U, 2= 2U, 3= 3U, 4= 4U	0-4	0
FU 13	Manual override permitted (without waiting for delay). This function allows starting the controller even the enable conditions are not met. The controller will switch off again if the running conditions are not met until the disable delay is expired.	ON/OFF	OFF
Fu 14	Enable delay (seconds)	0-1275s	0
Fu 15	Disable delay (seconds)	0-1275s	300
Fu 16	Range of limits: OFF = When limit 2 is greater than limit 1, enable when input value is greater than limit 2,disable when input value is less than limit 1. When limit 2 is less than limit 1, enable when input value less than limit 1, disable when input value is greater than limit 2. ON = When limit 2 is greater than limit 1enable when input value is between limit 1 and limit 2. When limit 2 is less than limit 1, enable when input value below limit 2 or above limit 1	ON/OFF	OFF
Fu 17	Input limit 1	per input	10
Fu 18	Input limit 2	Per input	90
Fu 19	Disable in case of alarms	Triangle shown =alarm selected	▽▽▽▽▽▽▽▽

- ➔ Enable or disable the controller based on desired input values, such as high or low temperature, occupancy sensor, window contact, etc. Can be used as *and* function where several conditions must be met before disable or enable. Time schedules do not override, but manual override is permitted. Delay times may be assigned for both enable and disable (allows for the controller to start before validation of operation values takes place). Set input limit 1 and 2 with options below. Example: With FU16=OFF, and Limit 2 > Limit 1, switch enable-to-disable at Limit 1, disable-to-enable at Limit 2.



Heating/cooling mode changeover

Parameter	Description	Range	Default
Fu 20	Select heat/cool changeover input (0=function disabled): 1= 1U, 2= 2U, 3= 3U, 4= 4U, 5= h/c status loop 1, 6= h/c status loop 2	0-6	0
Fu 21	Cooling activation delay (seconds)	0-1275s	300
Fu 22	Input limit 1	per input	20
Fu 23	Input limit 2	per input	40

- Switch heating/cooling state based on a universal input value. The input may be from a supply media (air or water) or outdoor air temperature sensor. For supply media temperature we recommend switching to cooling at 16 °C/61 °F and to heating at 28 °C/83 °F. For outdoor temperature we recommend switching to cooling at 28 °C/83 °F and to heating at 16 °C/61 °F outdoor temperature. These recommendations are given as suggestions. The ideal settings may be different on the actual project depending on climatic and system conditions.
- The change between heating and cooling is delayed to avoid unnecessary switching (FU21). Heat/cool status of one control loop may also be determined by the heat/cool state of the other loop (FU20= 5 or 6). The control loop used to determine the heat /cool state must be set to demand-based heating and cooling with (L23). Set limit 1 and limit 2 to switch between heating and cooling with options below. Example: When Limit 2 is greater than Limit 1, switch heat to cool at Limit 1, cool to heat at Limit 2. For binary open/close contact, open is a high value (100%), closed is a low value (0%).

